

Pixel detectors and fast timing with MAPS

Jory Sonneveld



Jory Sonneveld -- Nikhef detector R&D

CMOS monolithic active pixel sensors

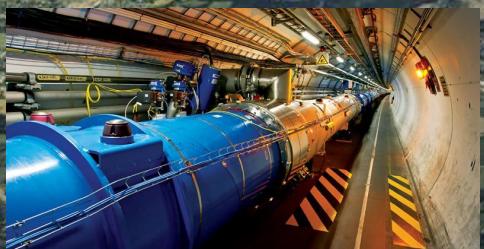


Where I used to work

And if they are interested...



Where I am:



LHC 27 km

With whom I work now



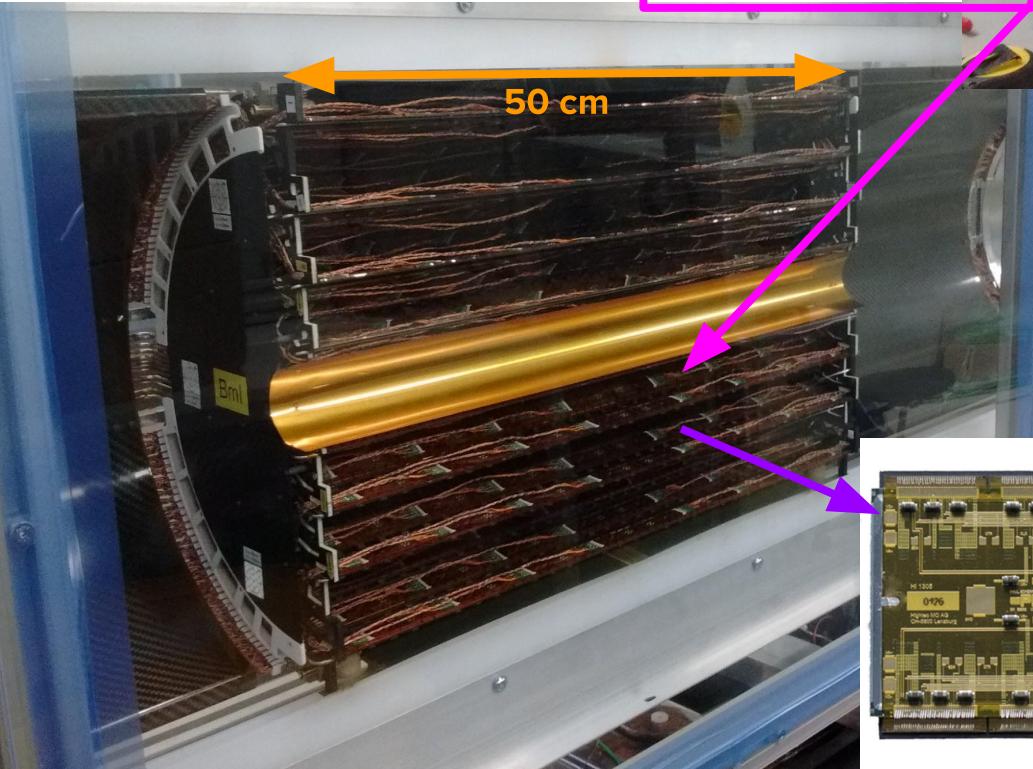
CMS pixel detector operations



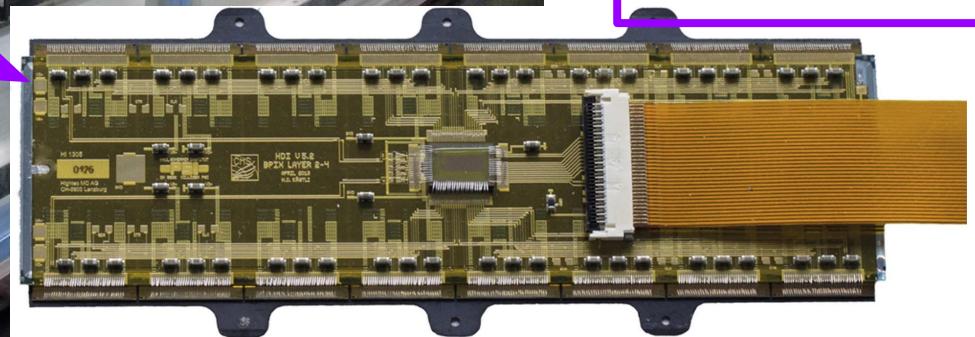
I worked in pixel operations to ensure this subdetector worked without problems with smooth data taking for good physics results
I did my master (at Nikhef) and PhD (in Aachen) in theoretical particle physics.

CMS pixel detector

Innermost layer is currently being replaced at CERN

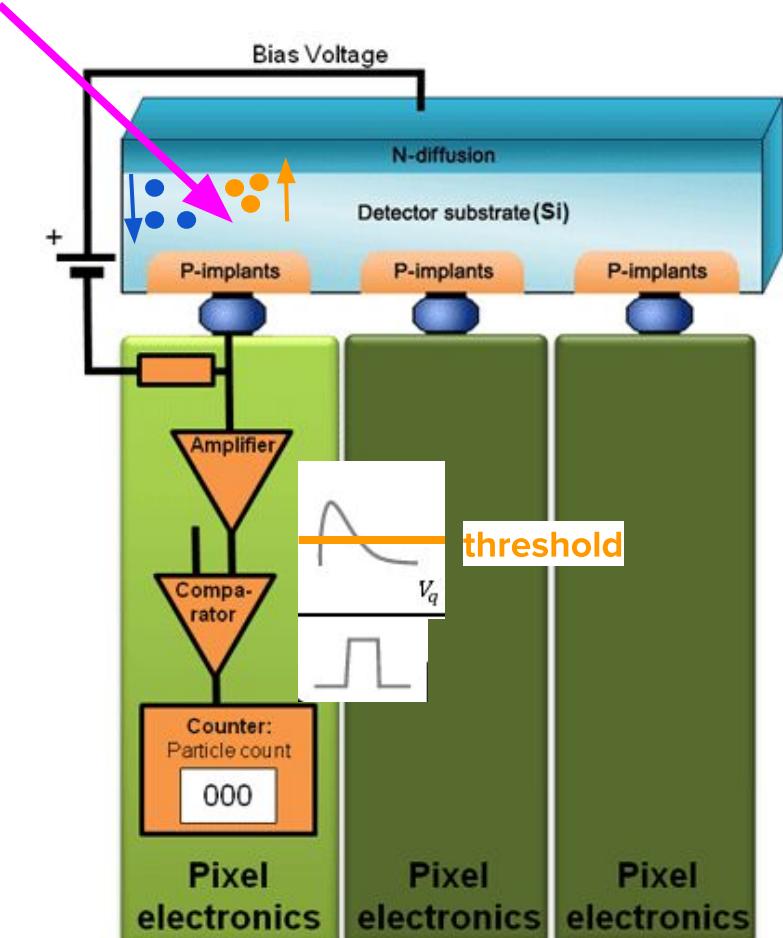
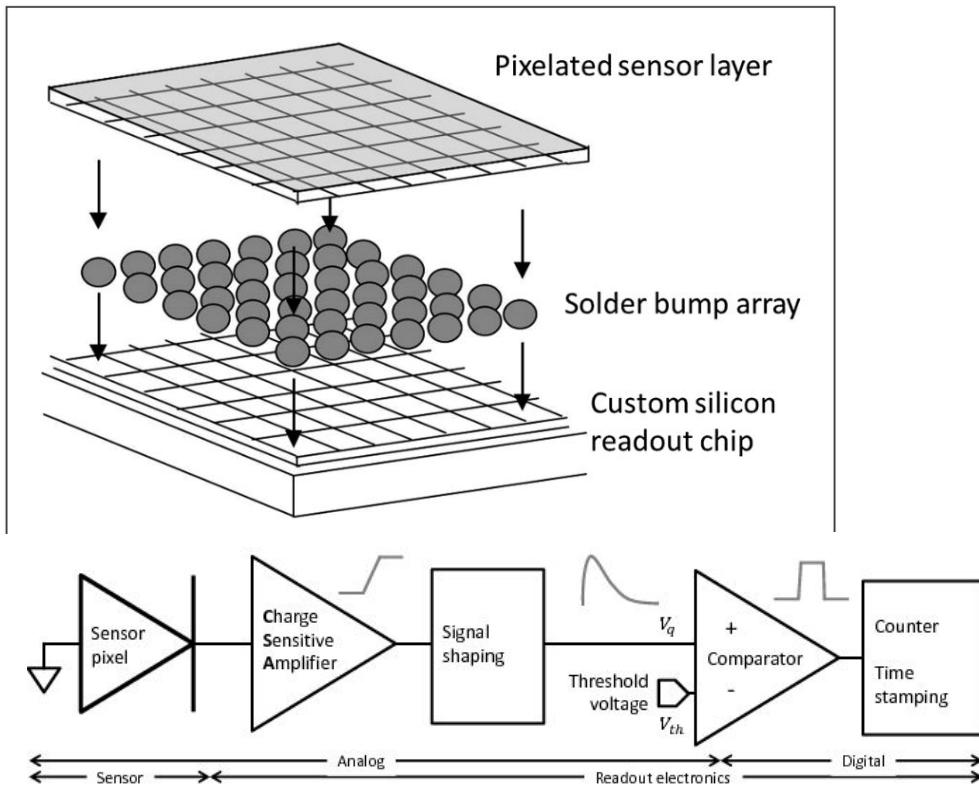


Services: DCDC converters,
conversion to optical signal...

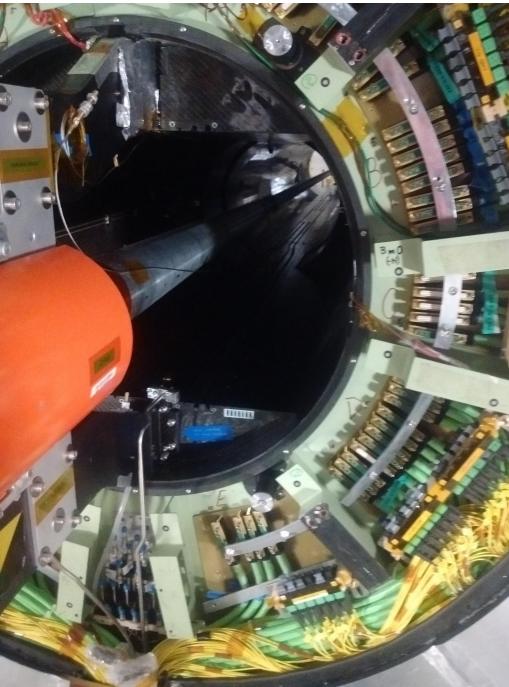
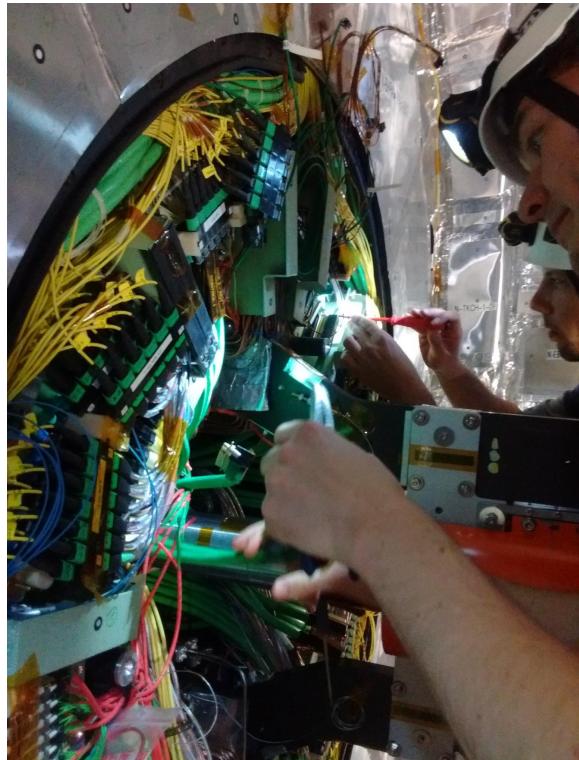


One “pixel detector”

A hybrid pixel detector



Pixel extraction January 2019



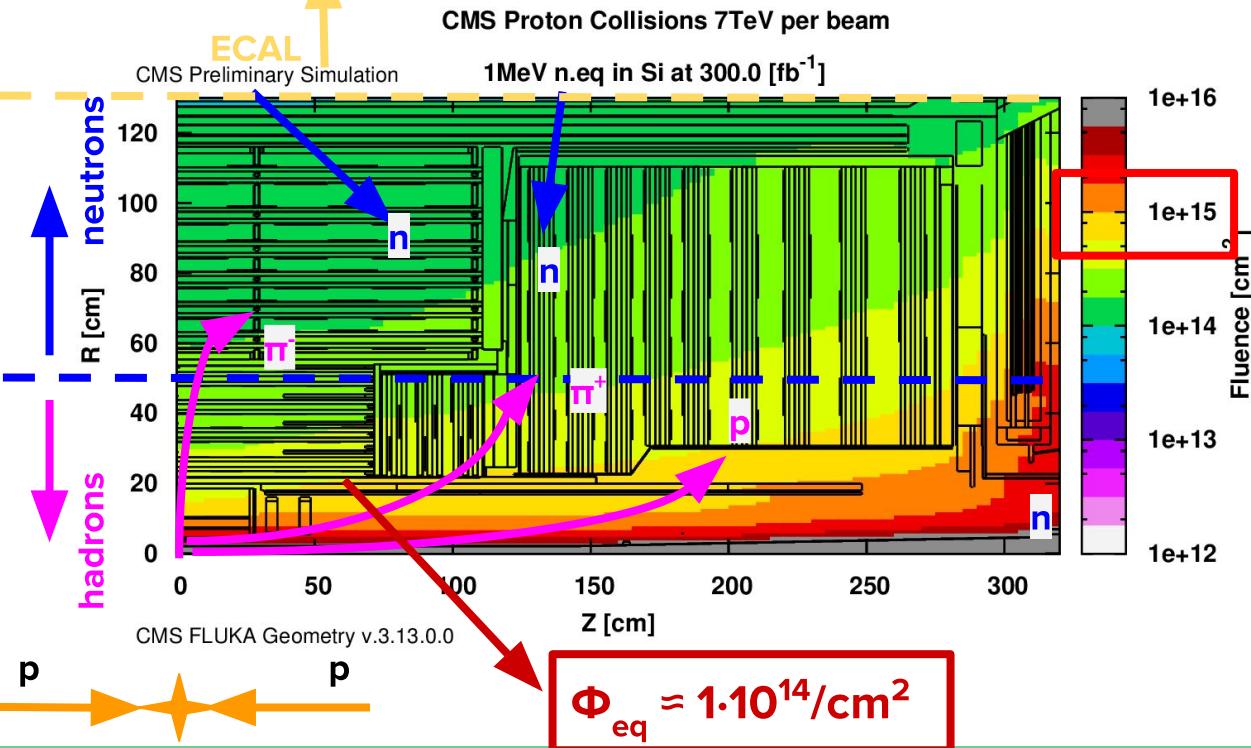
The CMS pixel detector was installed in 2017

Radiation damage modeling

LHC: a challenging environment

2017+2018: 118 fb^{-1}

2018: 68 fb^{-1}



Radiation effects are challenging for operations and performance:

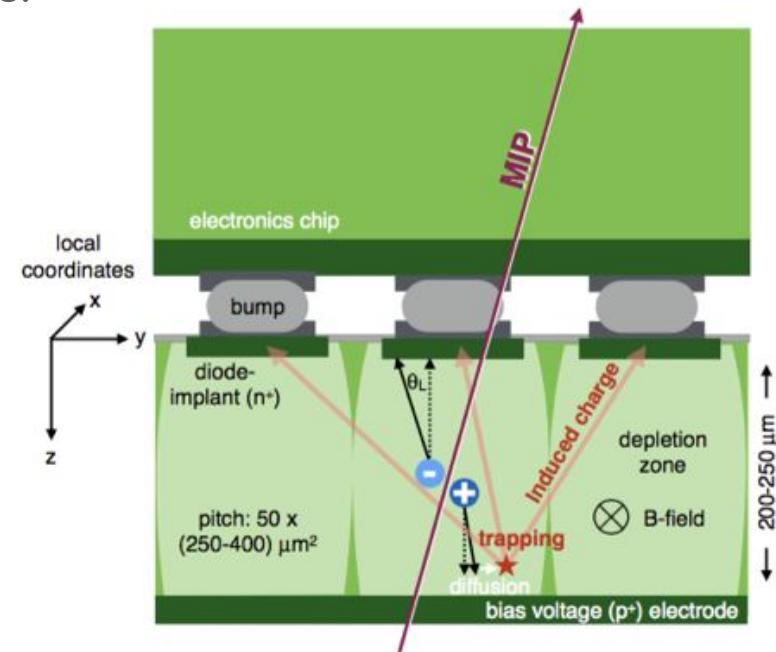
- Damage and single event upsets (SEUs) in electronics
 - false signals, chip damage
- Bulk defects cause change of space charge distribution
 - bias voltage increase
- Increasing leakage currents and heat dissipation
- Charge trapping in sensor:
 - decreasing charge collection efficiency

Φ_{eq} neutron equivalent number of particles per unit area

Not so ideal signal detection: radiation damage

Charges induced by an incident particle are collected with reduced efficiency as a result of radiation damage that causes:

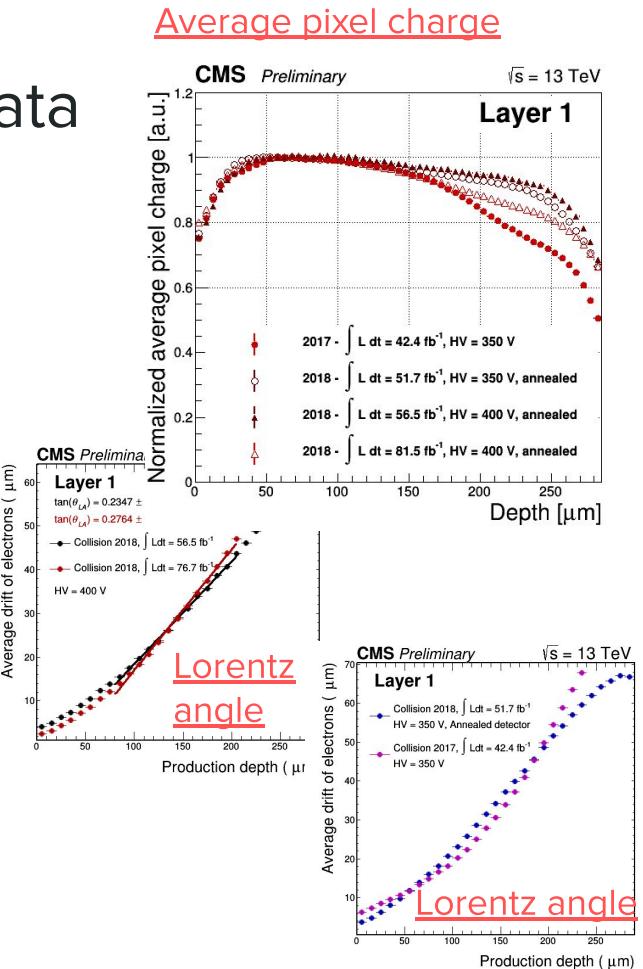
- **Deformation** of the electric field
- **Trapping** induces screening of charge
- Diffusion or annealing deflects the path:
Annealing
- Magnetic field, which changes with operational bias voltage and changing electric field, deflects the path:
Lorentz angle



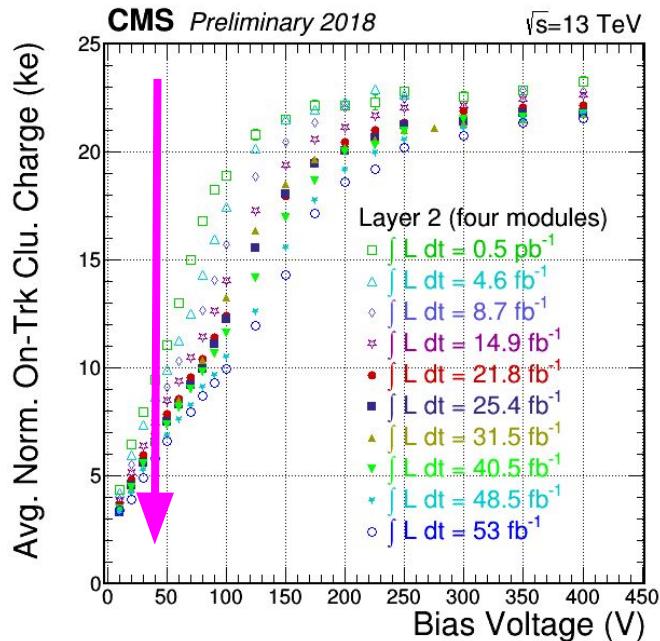
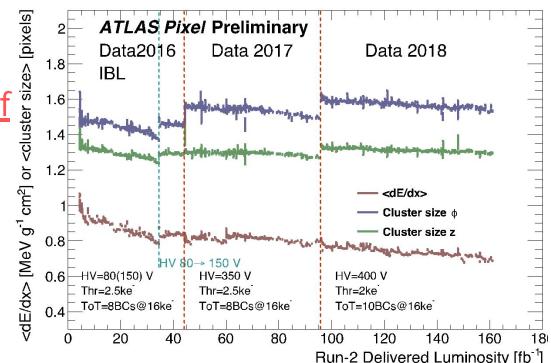
From Ben Nachman

Impact on data

Modeling radiation damage is important for performance (\rightarrow operational voltage) but also for physics

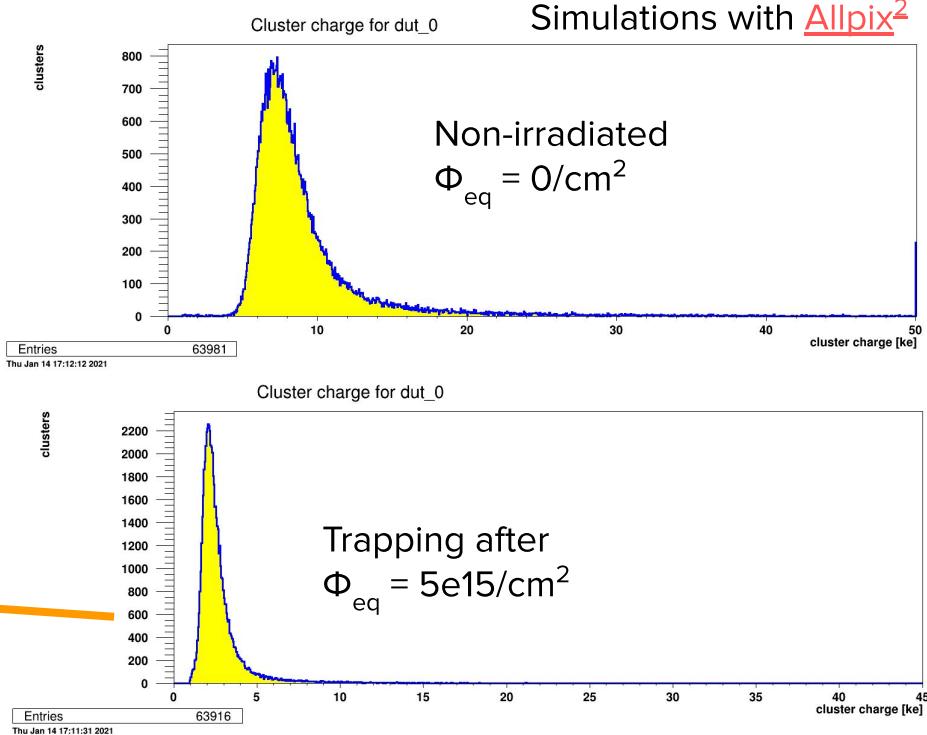
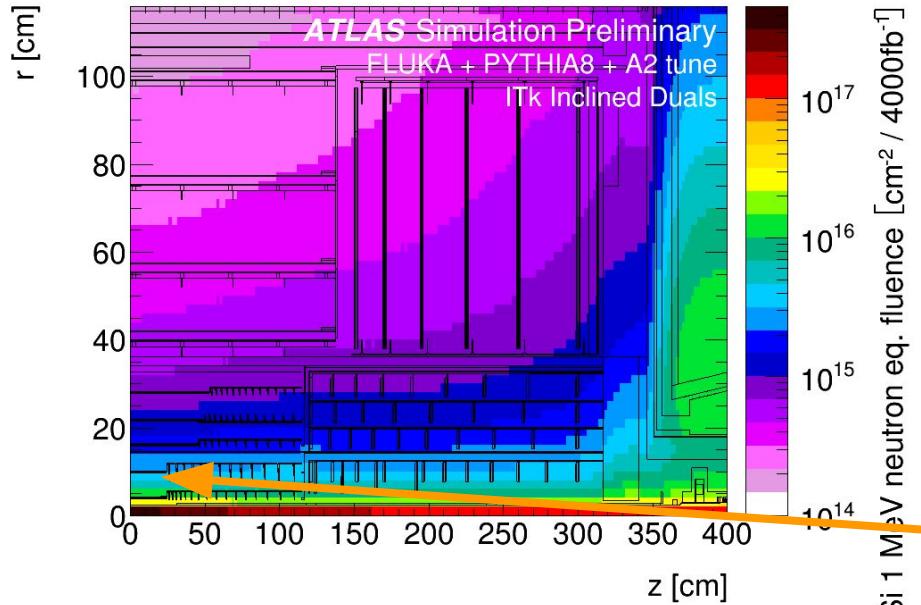


Significant decrease of dE/dx and cluster size for IBL



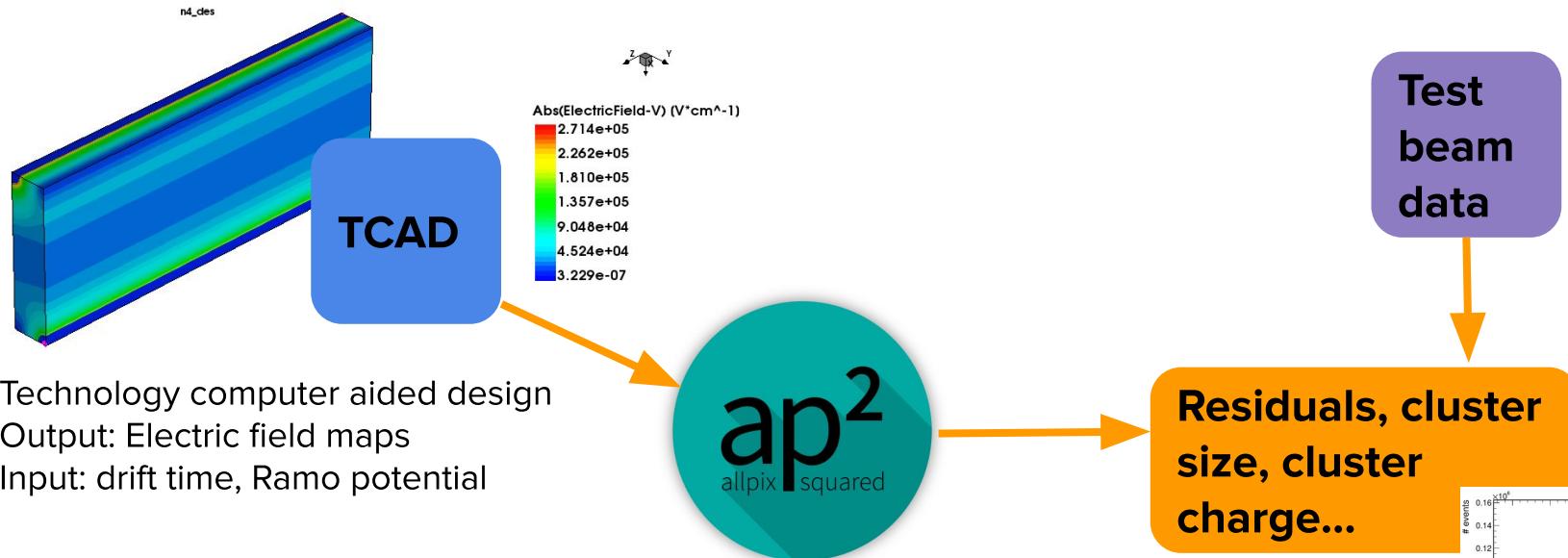
Radiation damage modeling for ATLAS ITk

ATLAS: modeling radiation damage



In the ATLAS group I work in the silicon radiation damage group on modeling trapping with Allpix²

Validate models with testbeam data and TCAD



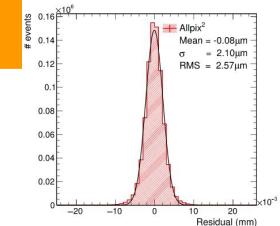
Allpix²: relies on ROOT, Geant4

Input: electric field, detector geometry

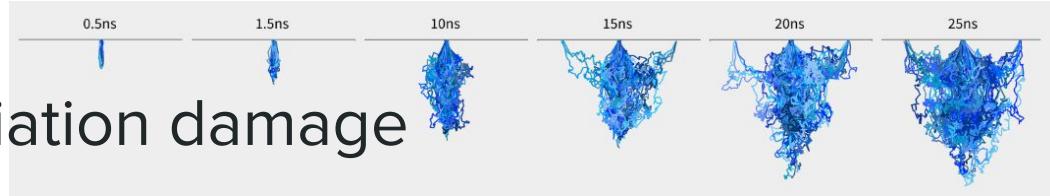
Output: corryvreckan, ROOT

Charge deposition, propagation, transfer, digitization

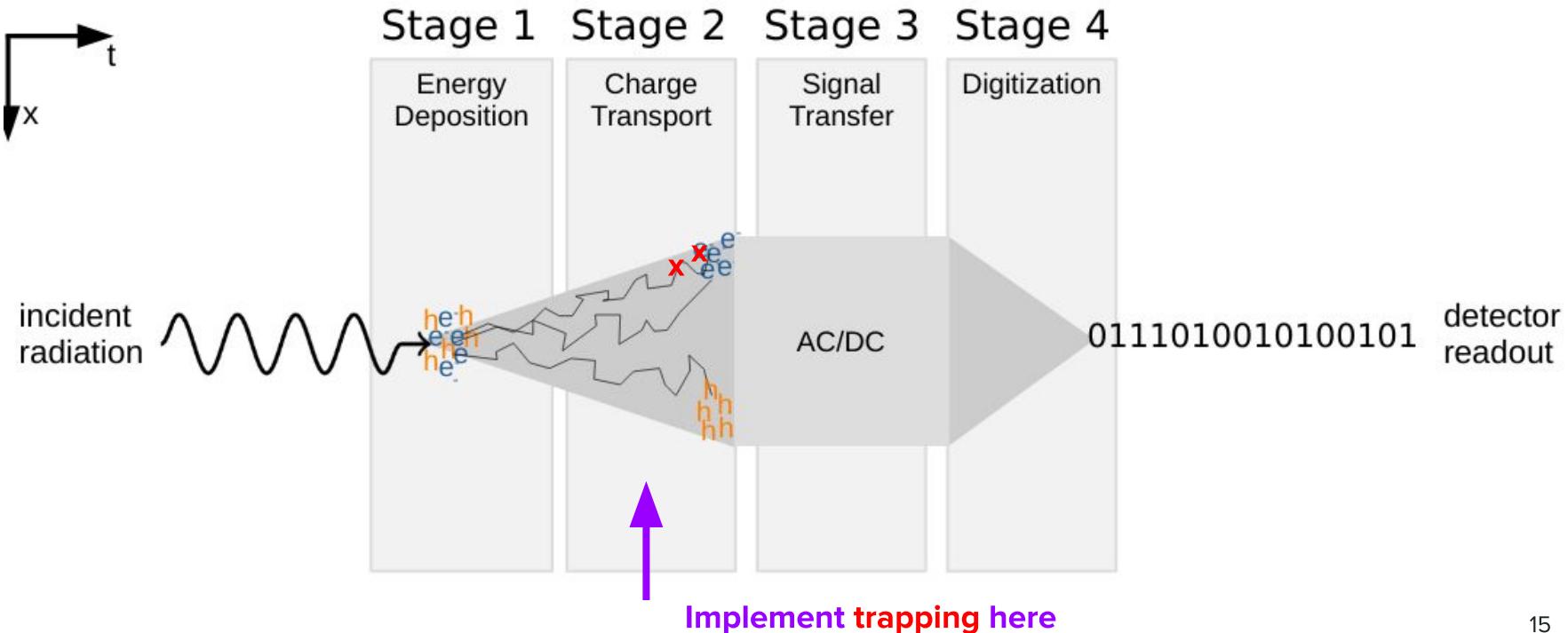
Implement trapping in charge propagation



Allpix² simulation with radiation damage

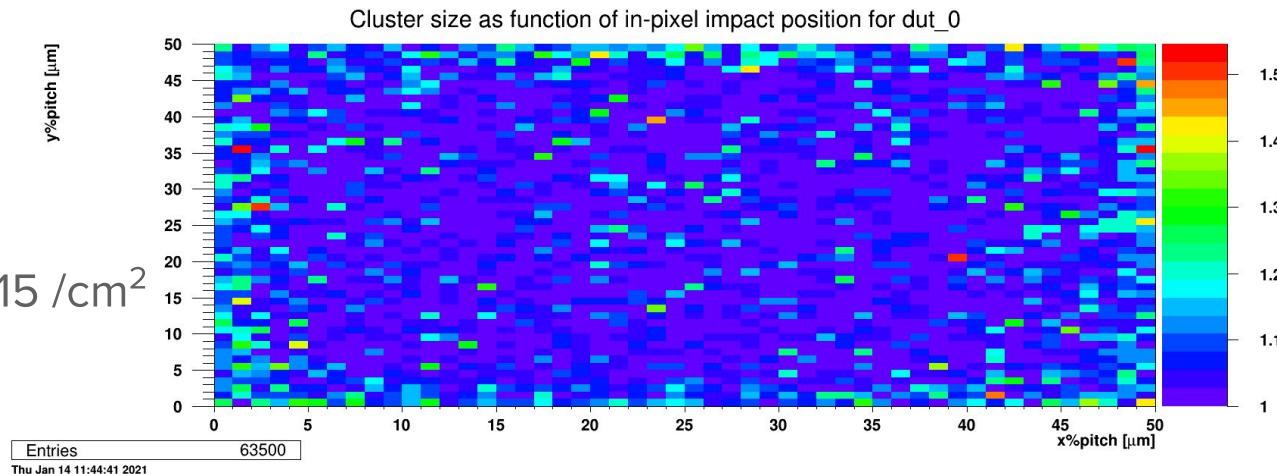
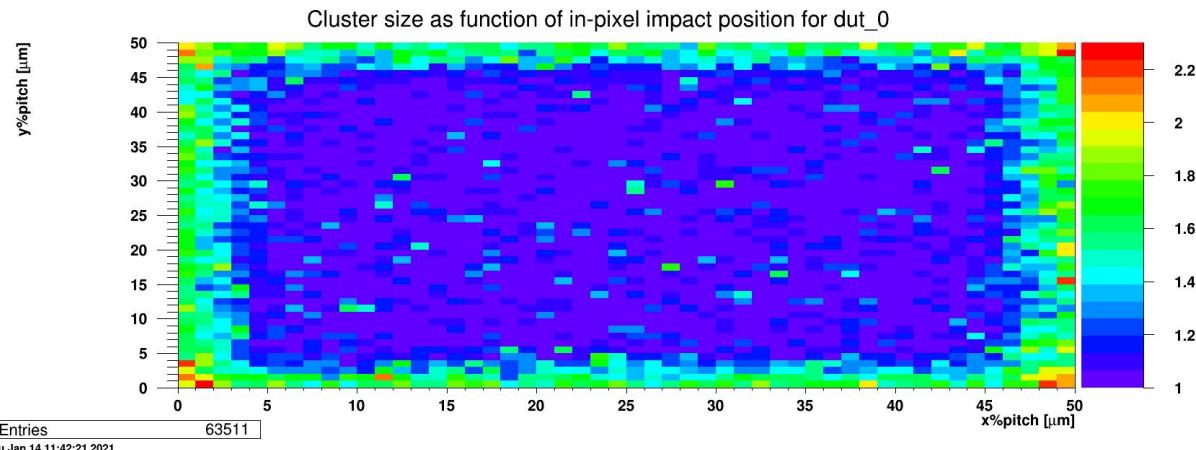


From Paul Schütze



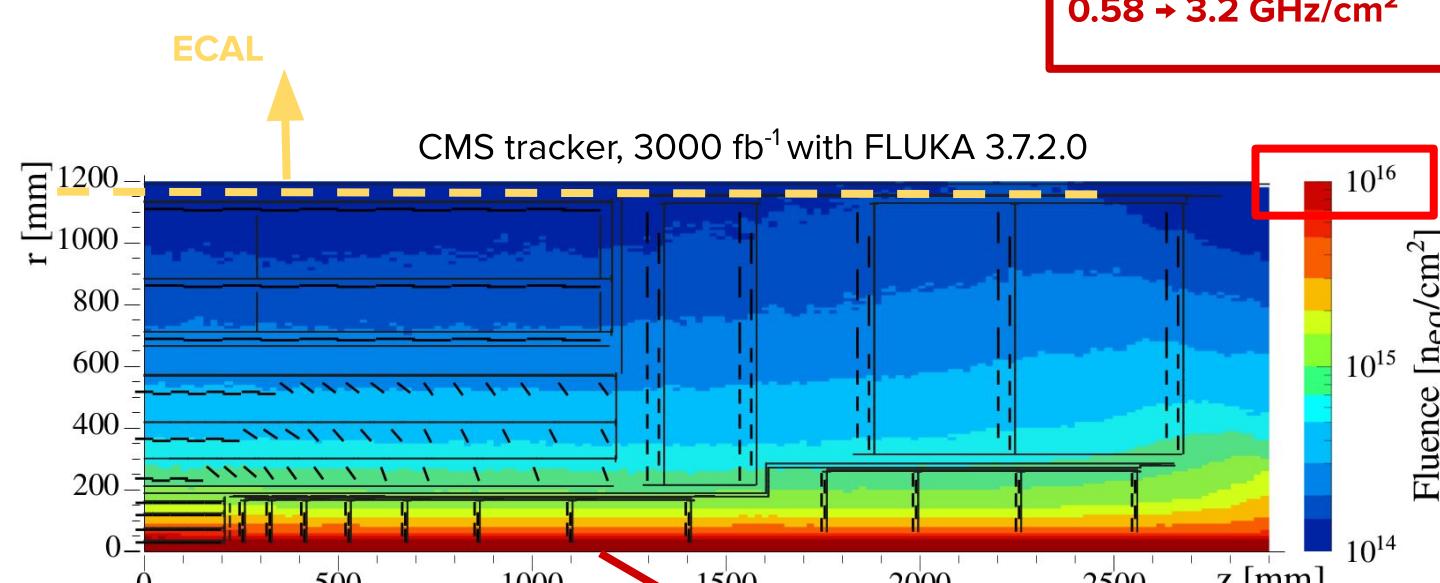
Cluster size

- Unirradiated
- 100k events
- DUT RD53
- Threshold 1000e⁻
- Trapping $\Phi_{eq} = 5e15 / \text{cm}^2$



Sensor characterization

High-luminosity-LHC: a challenging environment



5 × higher hit rate than in current detector:
0.58 → 3.2 GHz/cm²

Pileup up to 200
events per bunch
crossing at HL-LHC
Peak lumi up to
7.5e34/cm²/s

What is needed to
cope with these
fluences and rates?

$$\Phi_{\text{eq}} = 2.3 \cdot 10^{16} / \text{cm}^2$$

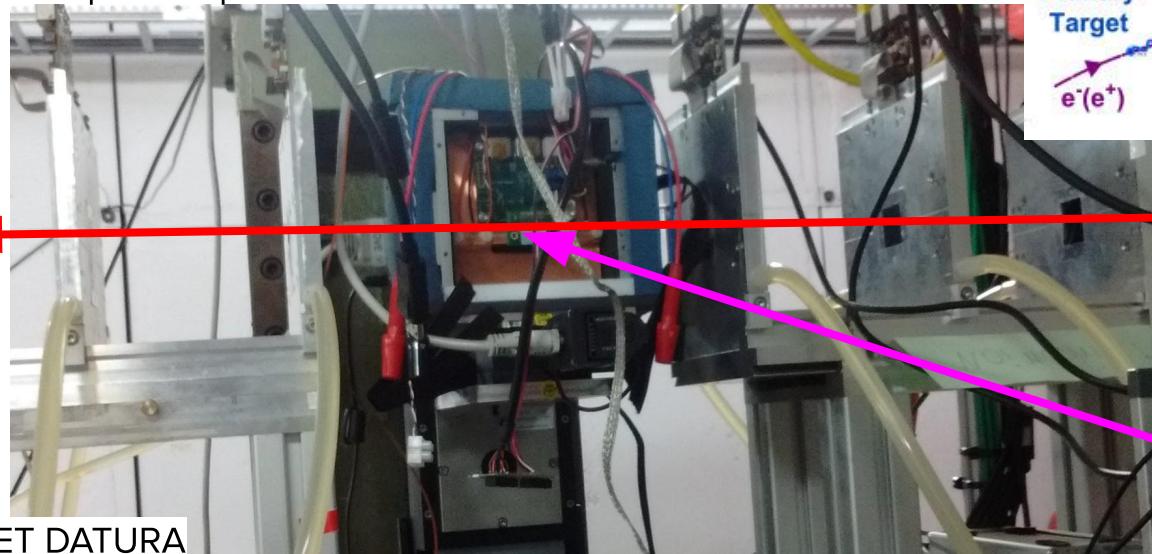
1.2 Grad



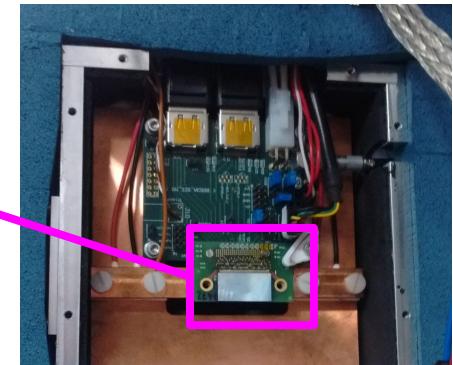
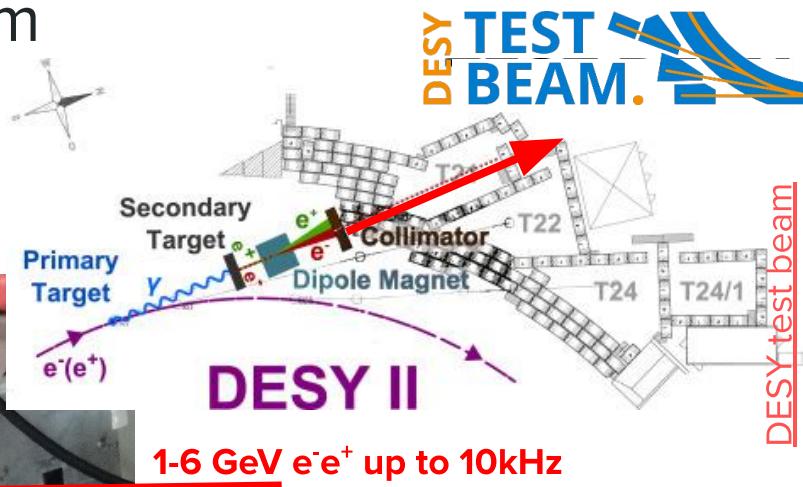
CMS-TDR-014

Sensor characterization at test beam

Tests of CMS phase 2 planar and 3D sensors on [RD53A](#) or [ROC4SENS](#) (R&D) chip as well as phase 1 pixel modules

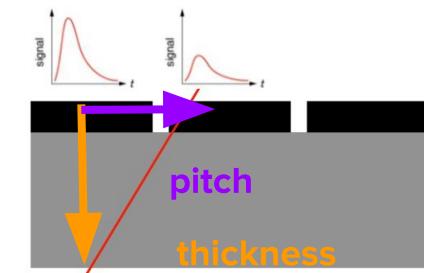
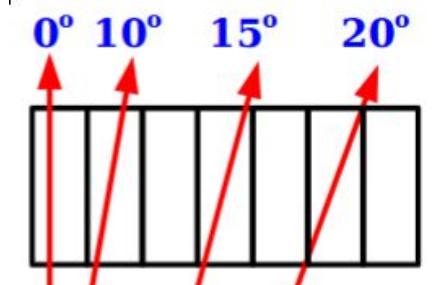
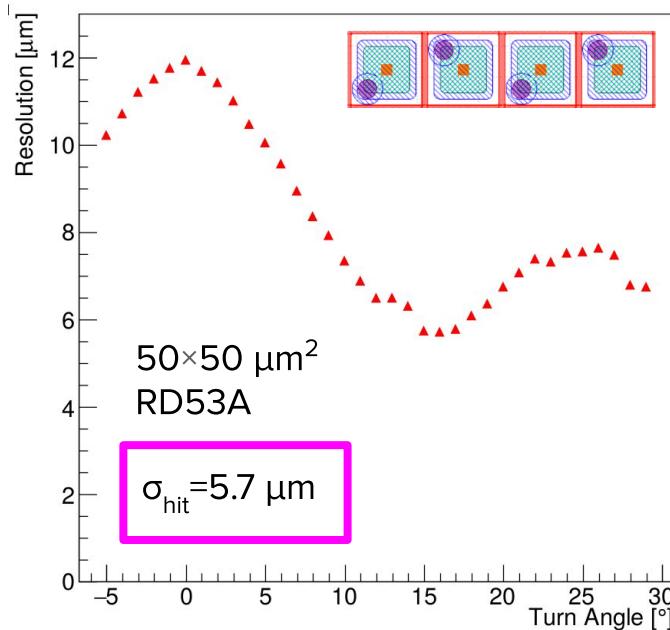


EUDET DATURA
telescope with 6
MIMOSA26 (MAPS for ILC, 50 μm thick, 18.4 μm^2) planes with resolution of 5.7 μm



Pixel cell dimensions and resolution of RD53A

- $25 \times 100 \mu\text{m}^2$ or $50 \times 50 \mu\text{m}^2$: charge sharing different
- **Best resolution: cluster size of 2**



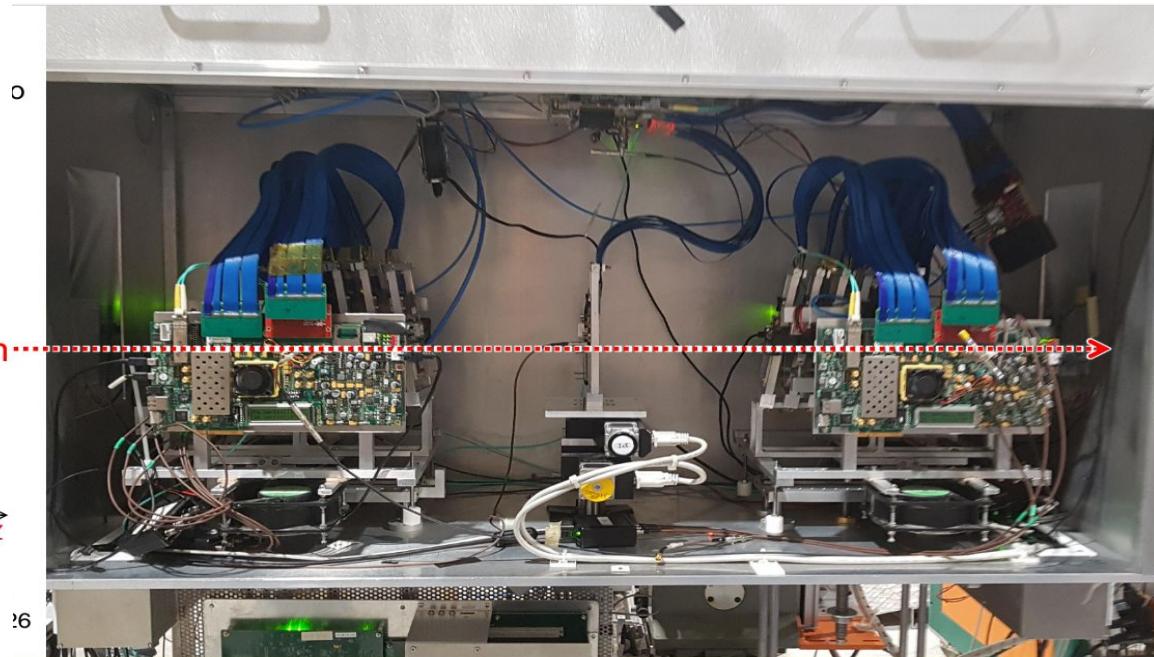
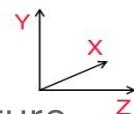
Optimal charge sharing at an angle $\text{atan}(\text{pitch}/\text{depth})$:

- **50×50 μm^2 :** $\text{atan}(50/150) = 18.4^\circ$
- **25×100 μm^2 :** $\text{atan}(25/150) = 9.5^\circ$

→ increase E-field with higher bias

Nikhef detector R&D: Timepix telescope

- Previously Nikhef built a fast Timepix 3 telescope for sensor and ASIC characterization
- 1.6 μm spatial resolution
- Track time resolution of 236 ps
- **Now we will build a Timepix 4 telescope with picosecond time resolution for characterization of fast detectors**
- And much more infrastructure in the lab for (3D) sensor characterization including a **TPA-TCT setup**

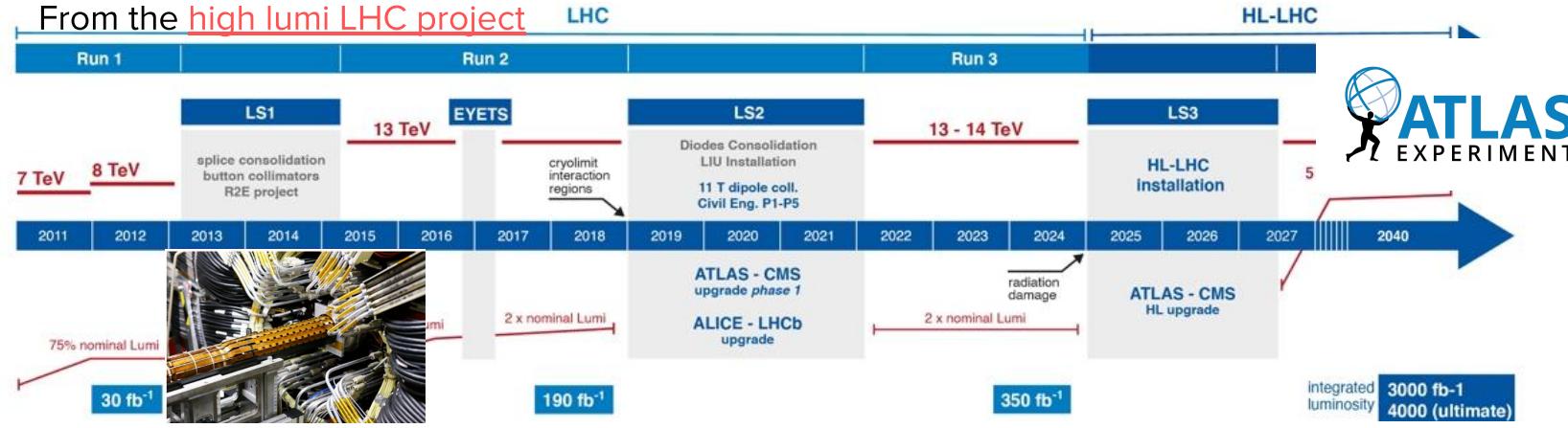


[K. Akiba et al 2019 JINST 14 P05026](#)
[K. Heijhoff et al 2020 JINST 15 P09035](#)

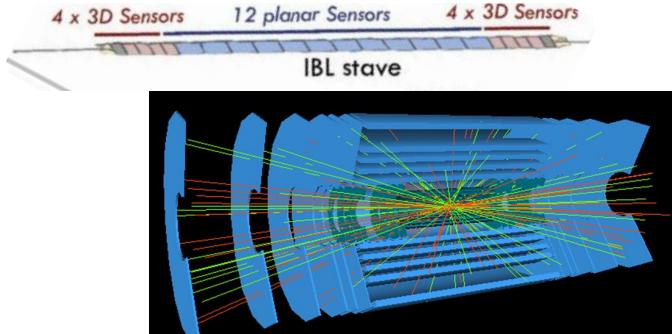
Fast timing in detector R&D group

LHC timeline

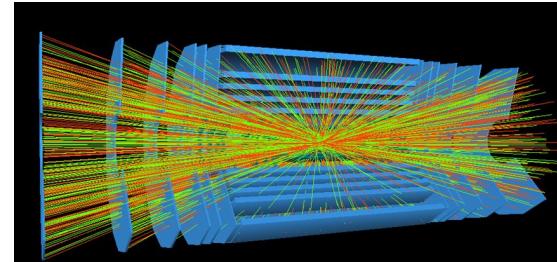
From the [high lumi LHC project](#)



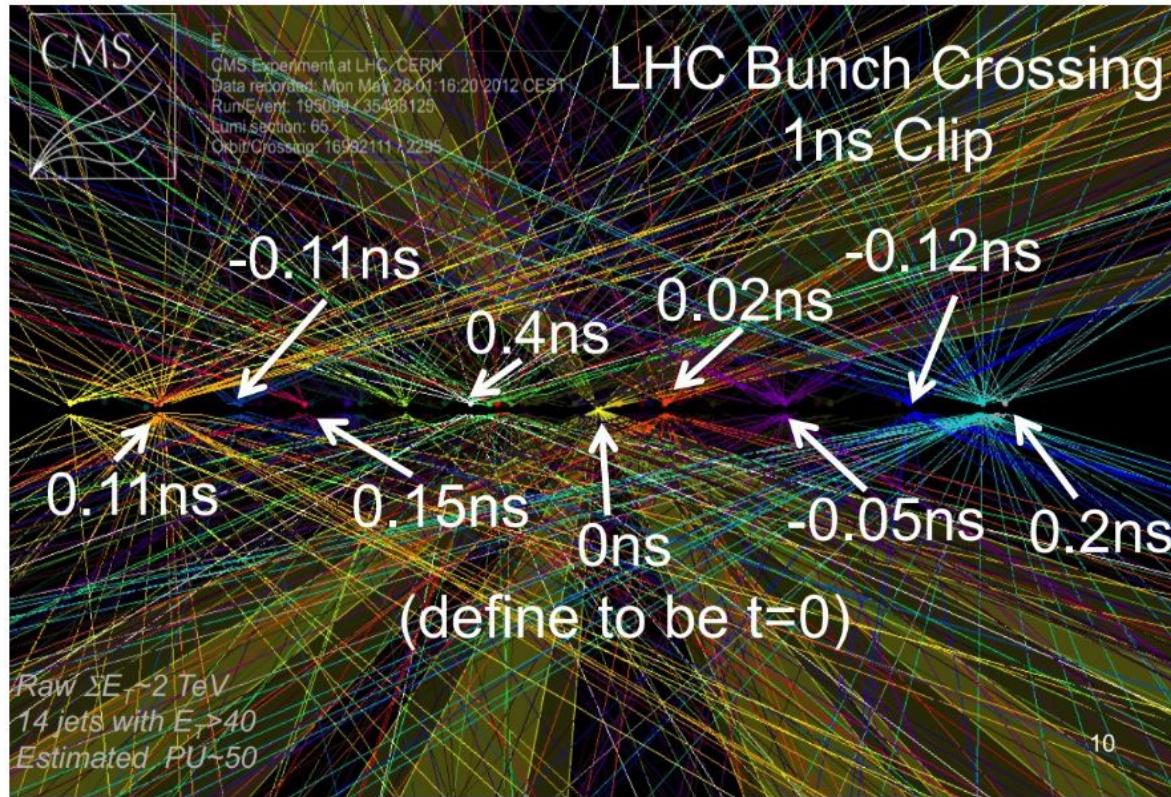
[From Kerstin Lantsch](#)



Pileup x 10
→

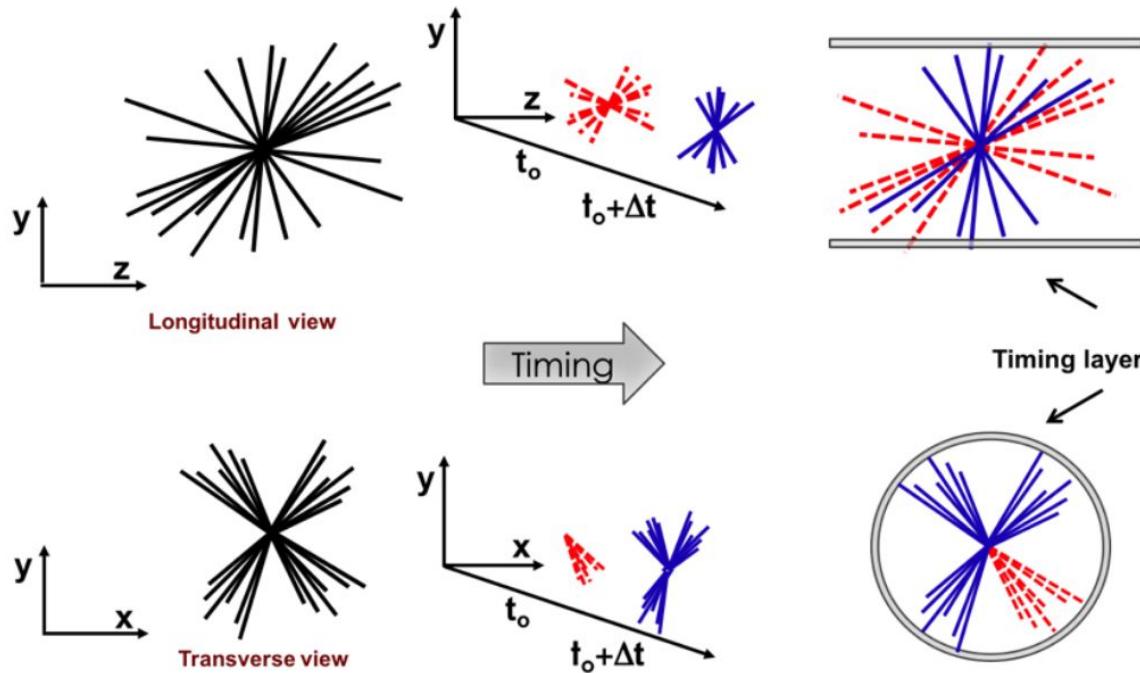


Why picosecond timing?



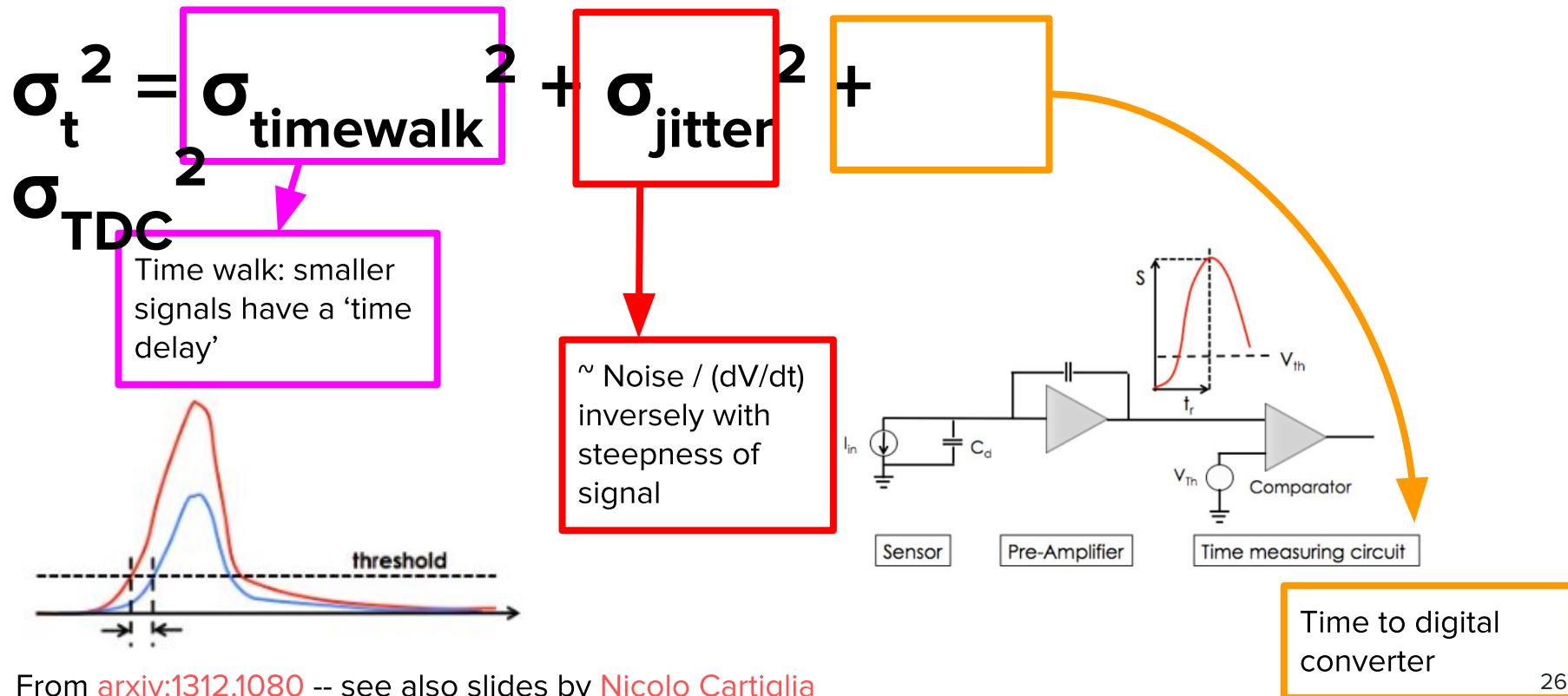
From [Nicolo Cartiglia](#)

Timing information from a timing layer



From [Nicolo Cartiglia](#)

Time resolution

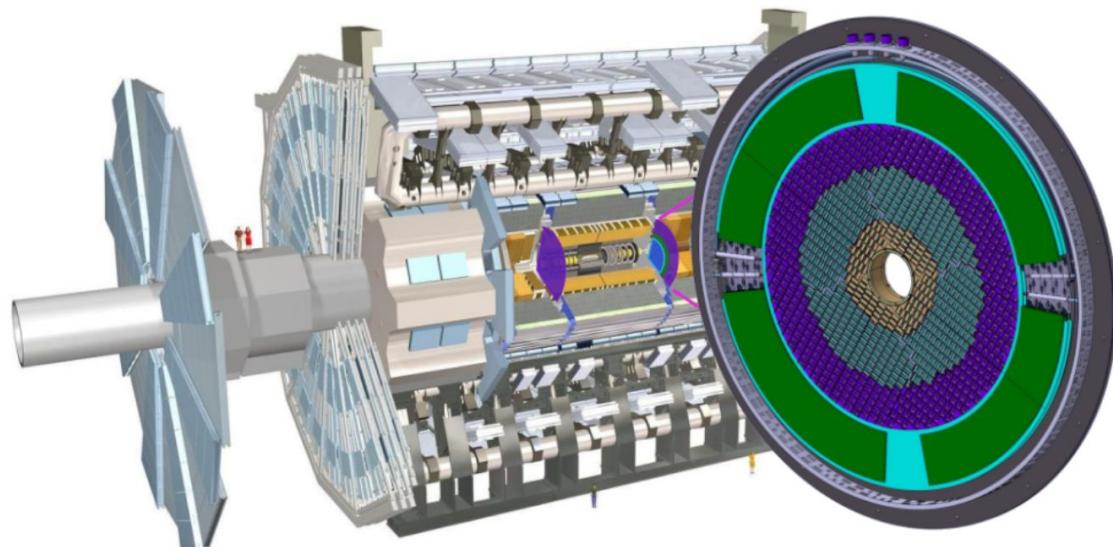
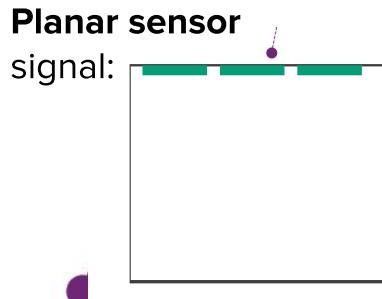


ATLAS High Granularity Timing Detector: a timing layer

TDR

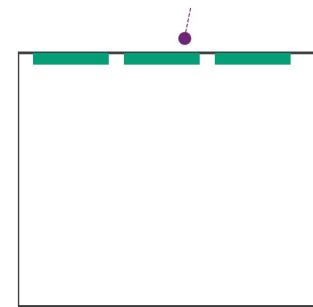
- **LGADs** with time resolution per track (per hit) 25 ps (35 ps) for $r = 120$ mm
- Half will be replaced after 1000 fb^{-1} : timing degrades with radiation damage

Low Gain Avalanche Diode
signal: charge is multiplied in gain layer! Animation by Robbert Geertsema



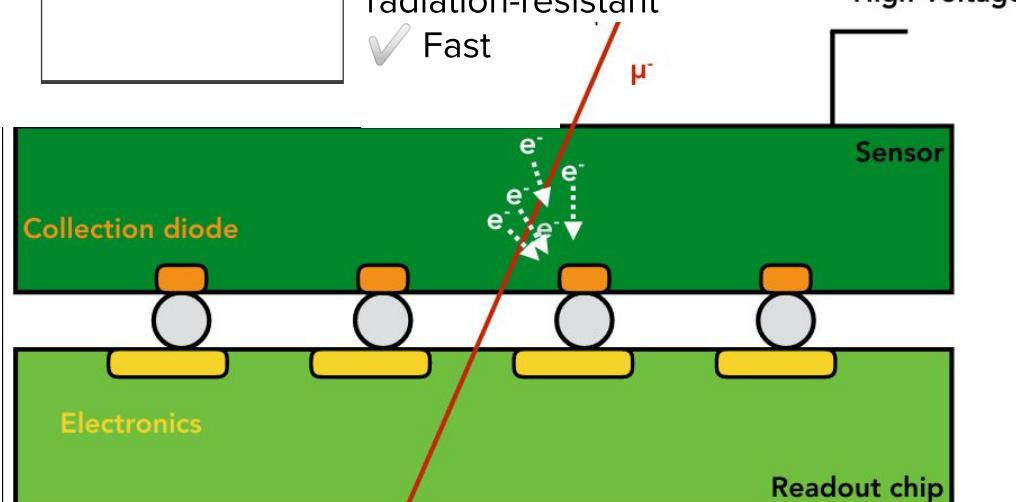
Animations courtesy of Robbert Geertsema

What are MAPS?



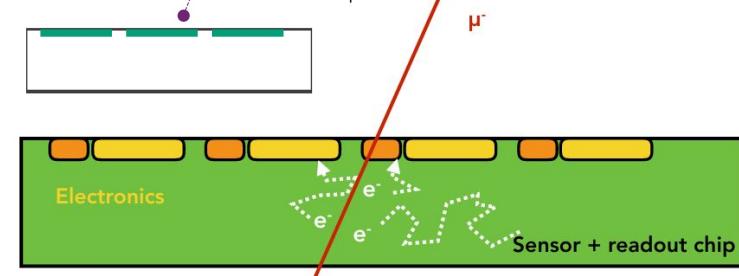
Planar hybrid sensor:

- ✗ Limited thickness for stability
- ✗ Limited pixel pitch
- ✗ Bump bonding costly
- ✓ But widely used and reliably radiation-resistant
- ✓ Fast

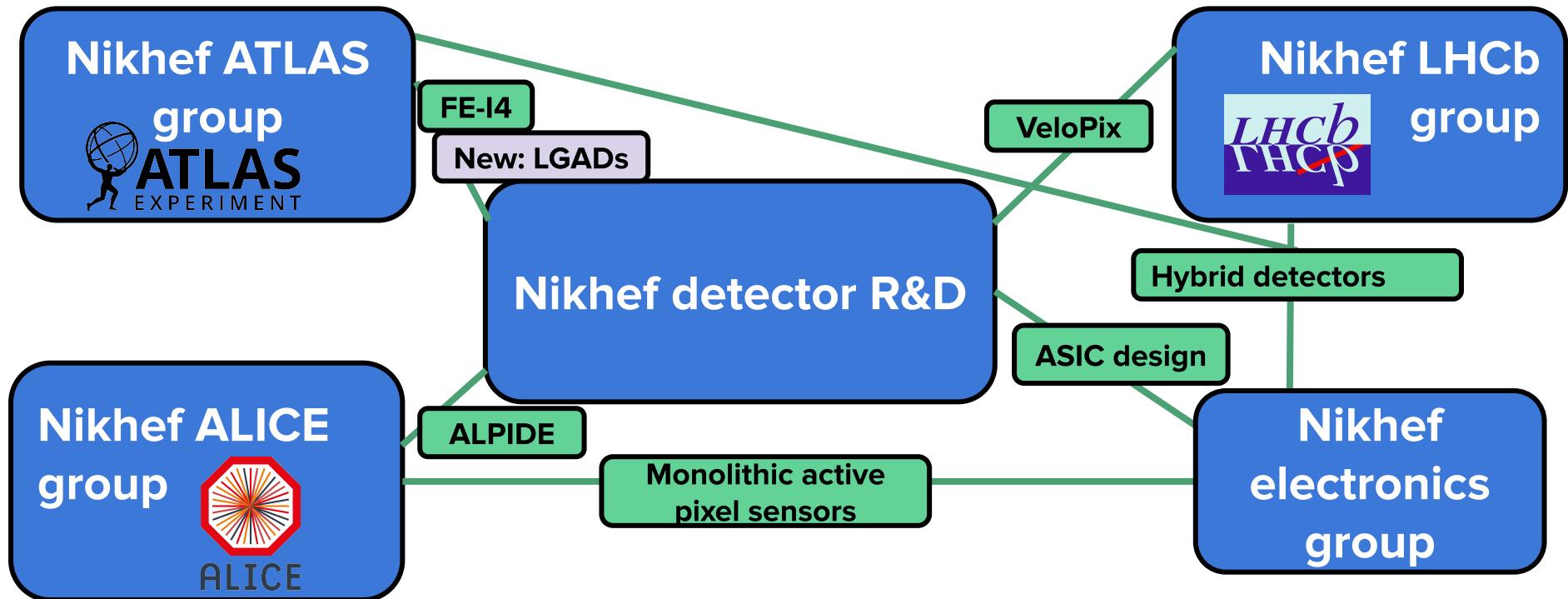


Monolithic sensor:

- ✓ Very little material
- ✓
- ✗ Limited depletion region: slow charge collection by diffusion **but this is improving**
- ✗ Not very radiation-hard **but this is improving**



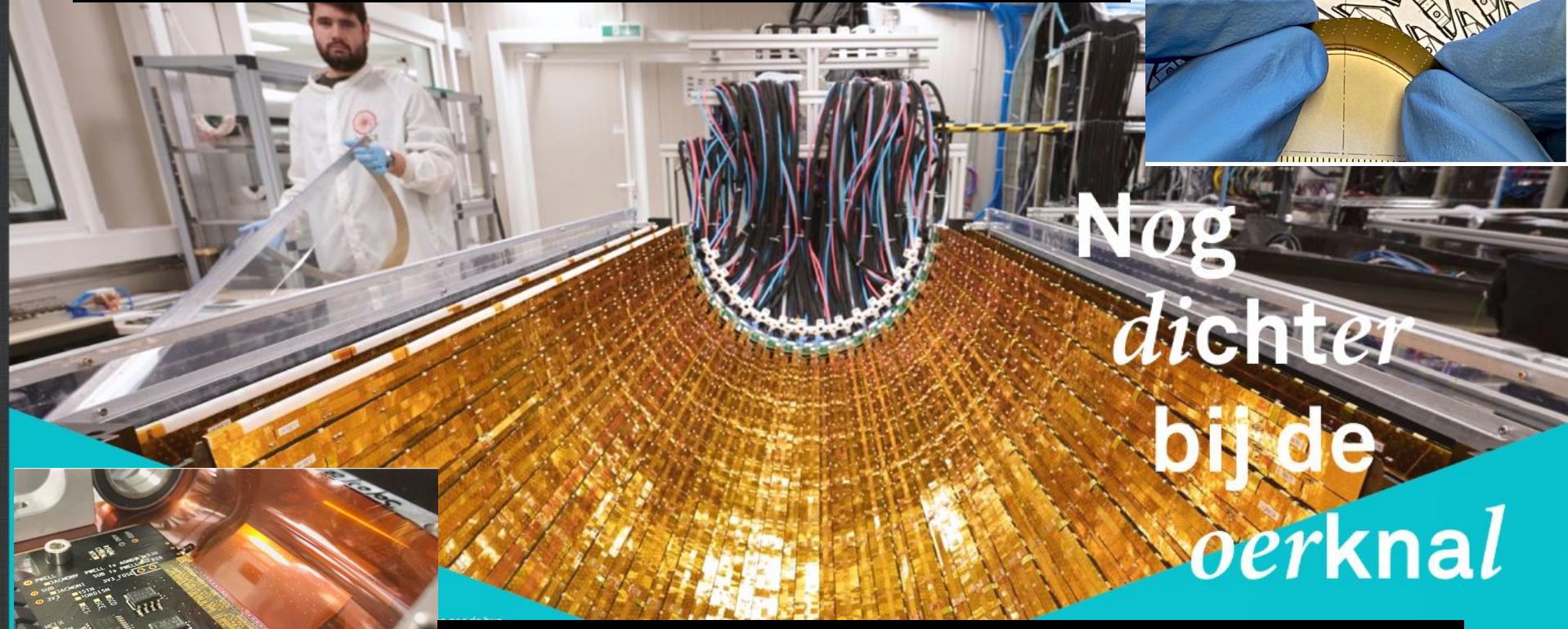
Nikhef detector R&D with Nikhef LHC groups



Work on fast timing in both MAPS and hybrid detectors

Fast timing and MAPS at the LHC

Our goal: fast timing with monolithic active pixel sensors



Nog
dichter
bij de
oerknal

ALICE inner tracking system 2: the first LHC experiment with MAPS, now being commissioned.

Het goud is overigens geen goud, maar polyimide-folie met ragdunne koperen voedingskabels voor de sensoren. Dun genoeg om vrijkomende

zijn ontstaan. ITS moet de betrappen die uit die zieden ontspannen en de fysici vertellen wat er daarbinnen precies gaande is.

botsingen preciezer worden bekijken.

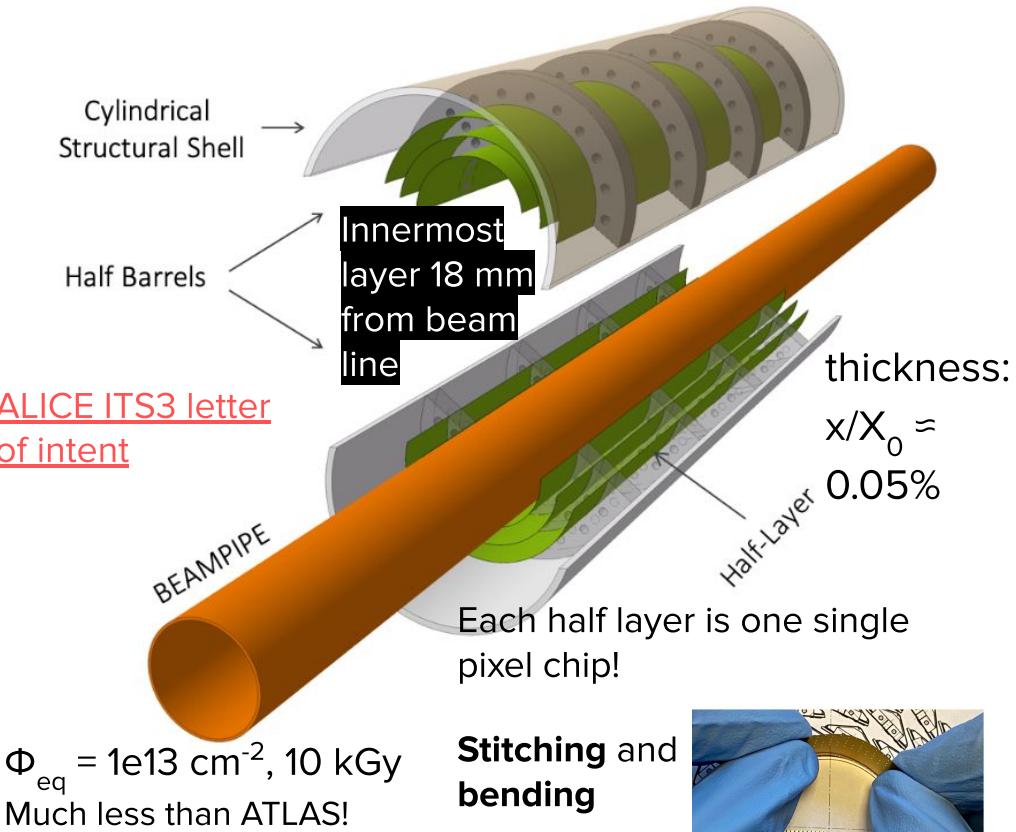
gemakkelijk honderd keer zoveel meetgegevens verzamelen als alles wat ALICE in

tijd. Het binnenste van de grote ondergrondse detector is vorig jaar meteen

toegevoegd. Deze sensorduigen zijn vorig najaar al in trillingsvrije kratten van Amsterdam

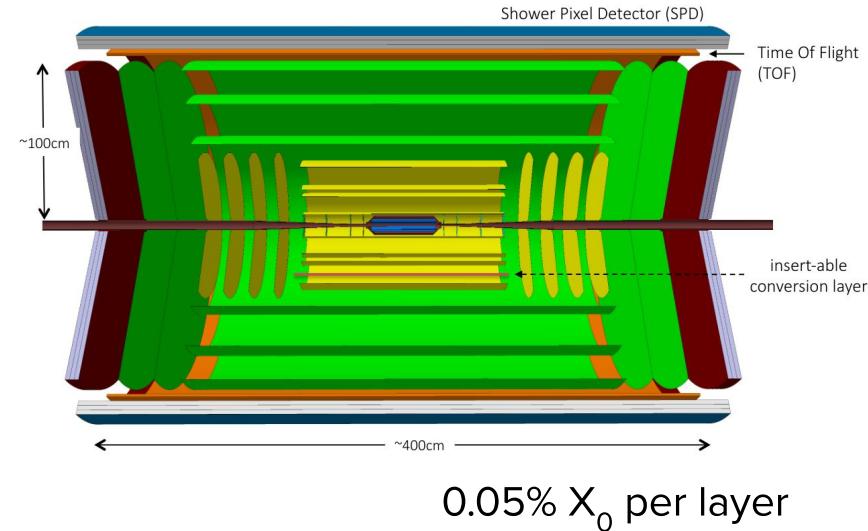
gen. Een kwart
agen nummer 6
ef in
leden van het
geduld de koo-
oor stuk 31

ALICE ITS3: 2025



ALICE3: 2030

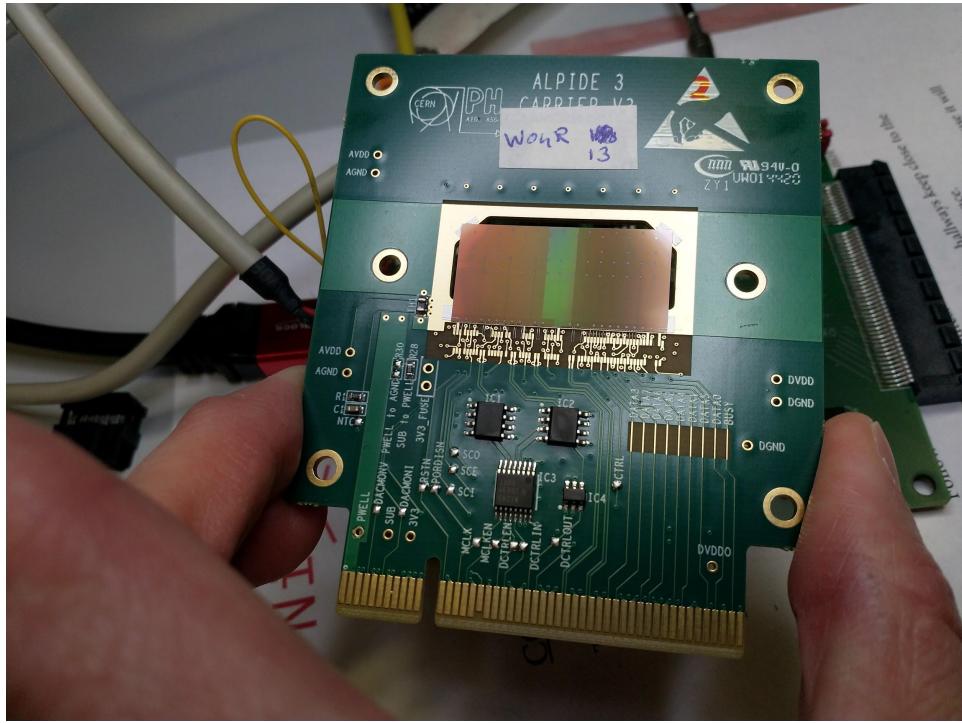
ALICE3 expression of interest
<https://arxiv.org/pdf/1902.01211.pdf>



Time of flight detector with 20 ps time resolution -- possibly depleted MAPS:
 $\Phi_{eq} = 1e12 \text{ cm}^{-2}$

ALPIDE chips in the Nikhef R&D lab

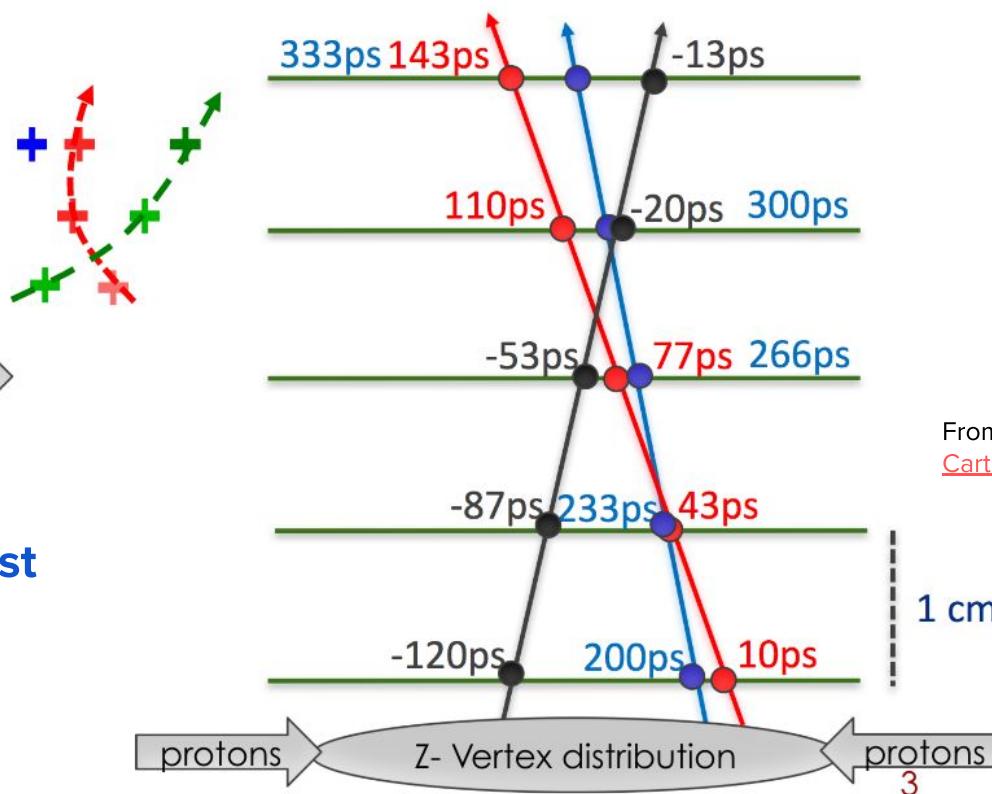
With Roberto Russo:
measurement and simulation of
ALICE ALPIDE time resolution



Timing at points along the track

+++
++
++

Timing



MAPS in ATLAS ITk innermost layers in 2035?

From Nicolo
Cartiglia

1 cm

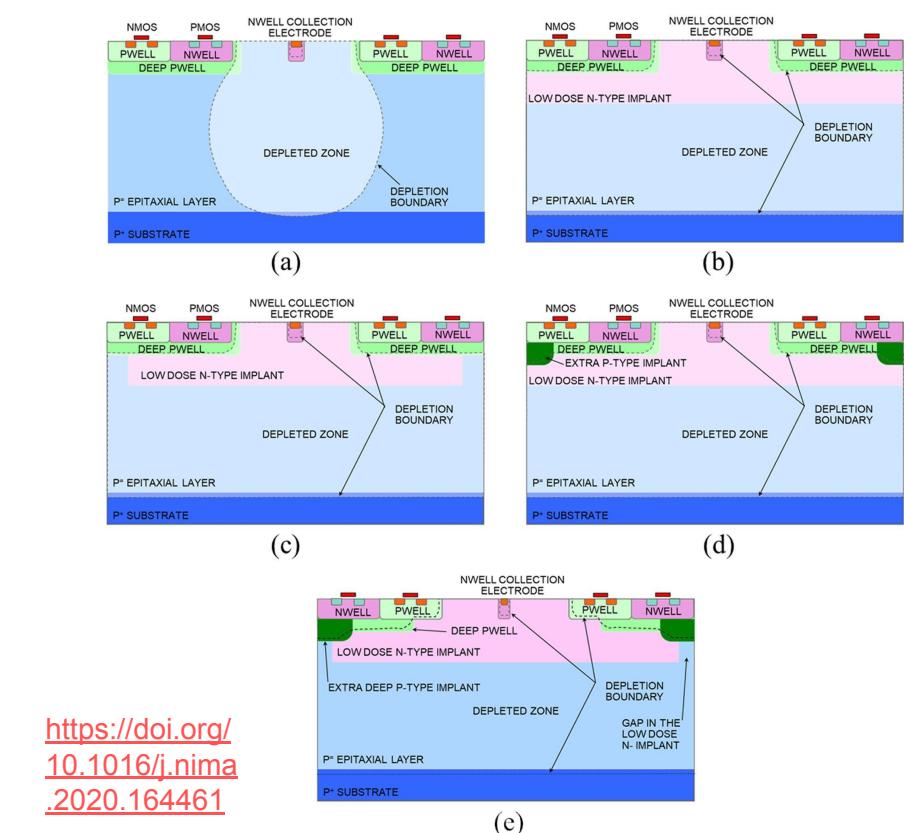
Fast MAPS example: FASTPIX

FASTPIX: coming soon

- tens of ps
- 20 uW power consumption

See also talk by
Magdalena Munker
now at 11:00:
<https://indico.cern.ch/event/997569/>

Many groups looking into MAPS + fast timing.
Other examples: [ARCADIA](#), [MonPicoAD](#)



[https://doi.org/
10.1016/j.nima
.2020.164461](https://doi.org/10.1016/j.nima.2020.164461)

HV CMOS MAPS

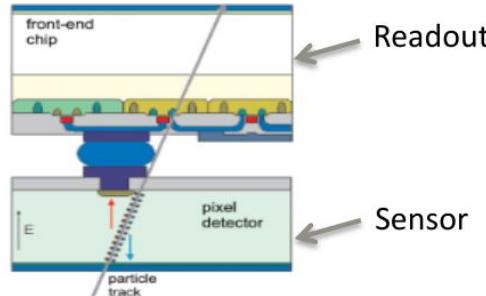
Radiation hard depleted MAPS

ALICE ALPIDE is a
low-resistivity CMOS chip:
back bias up to maximum 6 V.
Small collection electrode.

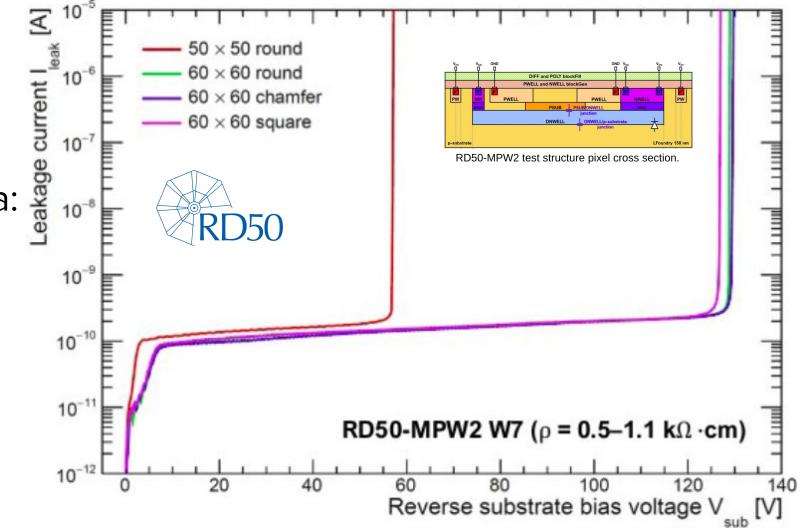
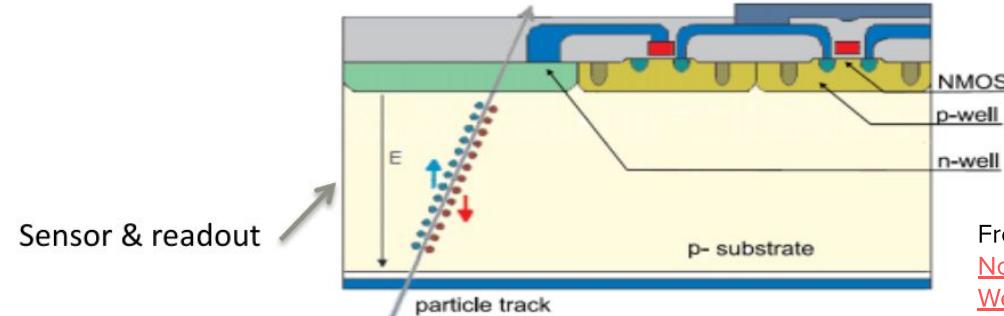
With Christina Tsolanta:
measurement and
simulation of time
resolution for RD50
MPW2 HV CMOS test
structure.

HV CMOS or depleted MAPS (DMAPS) can have a much higher
bias voltage and larger collection electrode:
fast collection time and **radiation tolerant**.

Hybrid detector



Depleted monolithic active pixel sensor (CMOS)



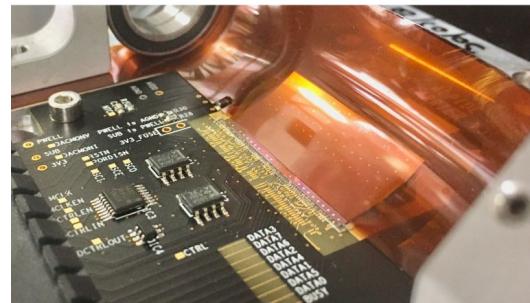
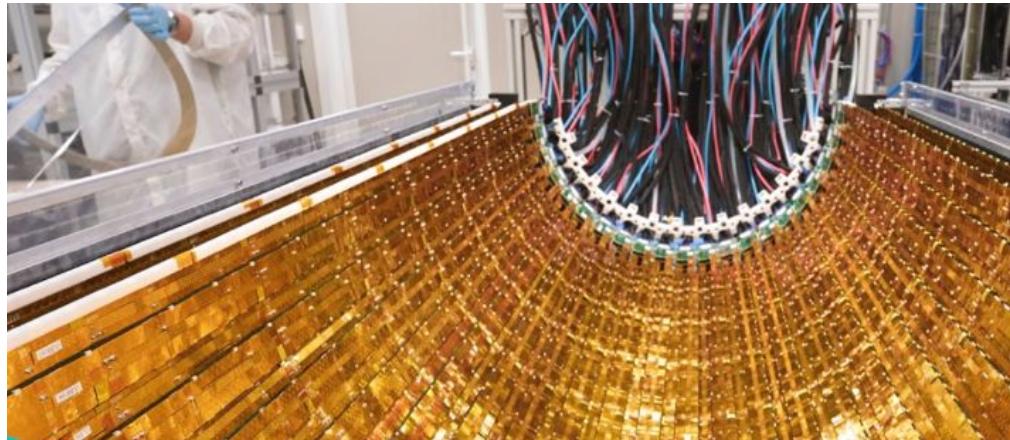
From [Ricardo
Marco
Hernández](#)

MAPS are the future

4D tracking is the future

One option is monolithic active pixel sensors: they are

- Thin
- Cheap
- Large collection electrode like RD50 depleted MAPS:
 - High breakdown voltage
 - Large signal
 - Radiation tolerant
- Small collection electrode like ALPIDE:
 - Low capacitance
 - Low noise
 - Low power
 - Radiation hardness in sight
 - We will contribute to time resolution measurements



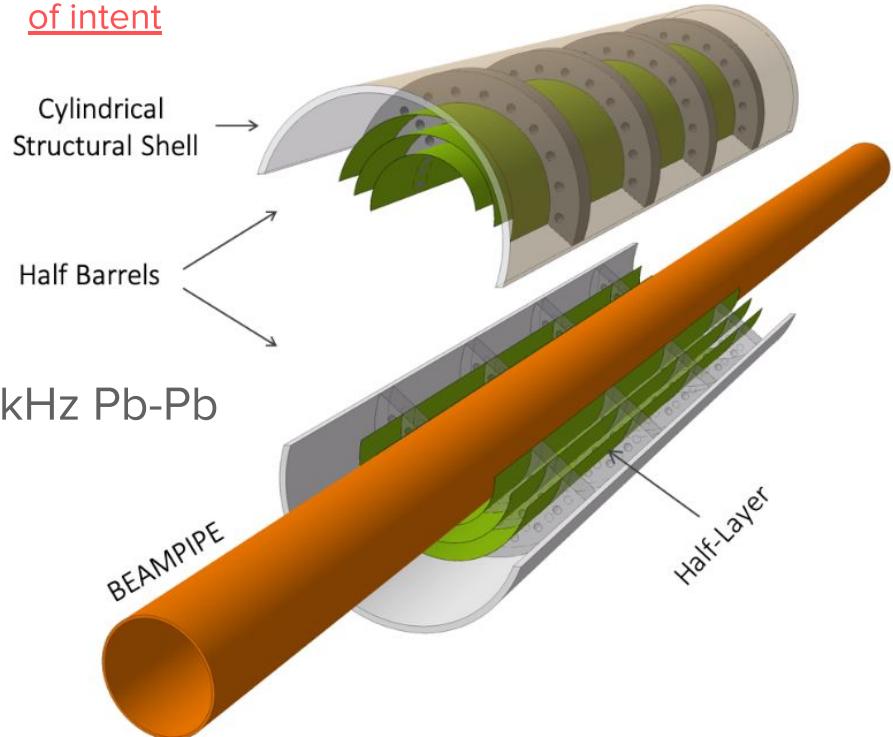
Additional material

ALICE ITS3

Each half layer is one single pixel chip!

- Innermost layer 18 mm from beam line
- For 50 μm thickness: $x/X_0 \approx 0.05\%$
- Target thickness: 20-40 μm
- Occupancy $1\text{e}-3 \rightarrow 2.2 \text{ MHz cm}^{-2}$ for 50 kHz Pb-Pb
- 5 μm resolution
- 1 μs integration time
- $\Phi_{\text{eq}} = 1\text{e}13 \text{ cm}^{-2}$, 10 kGy
- Power requirement 20 mW cm^{-2}
- 7 mW cm^{-2} in pixel matrix
- 150 mW cm^{-2} digital periphery

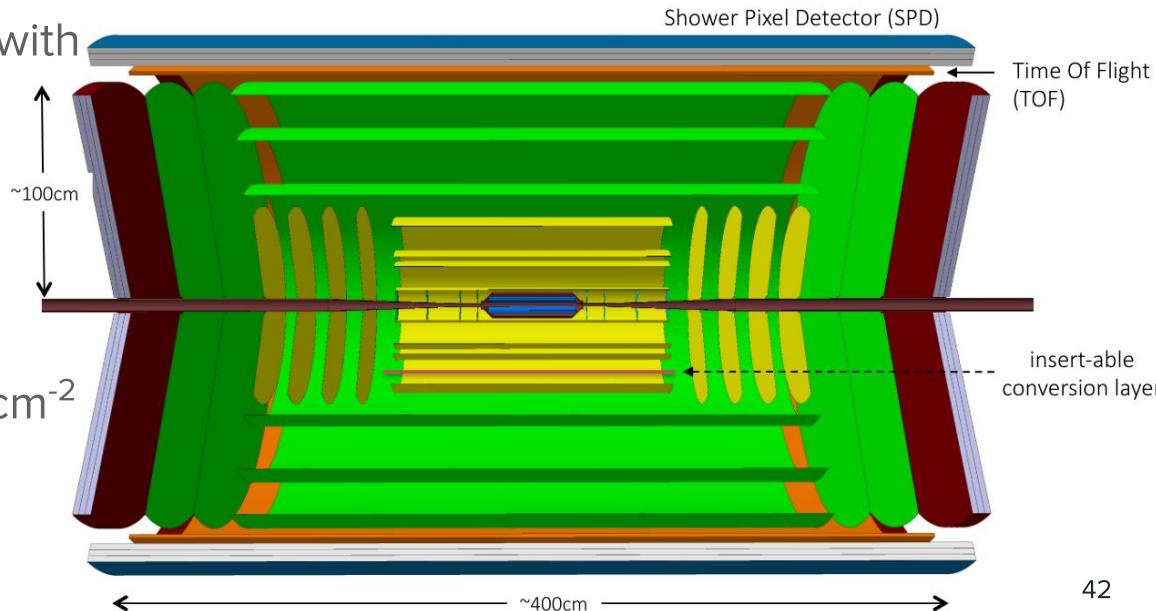
ALICE ITS3 letter
of intent

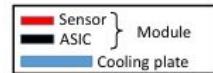


ALICE ITS4

ALICE expression of interest
<https://arxiv.org/pdf/1902.01211.pdf>

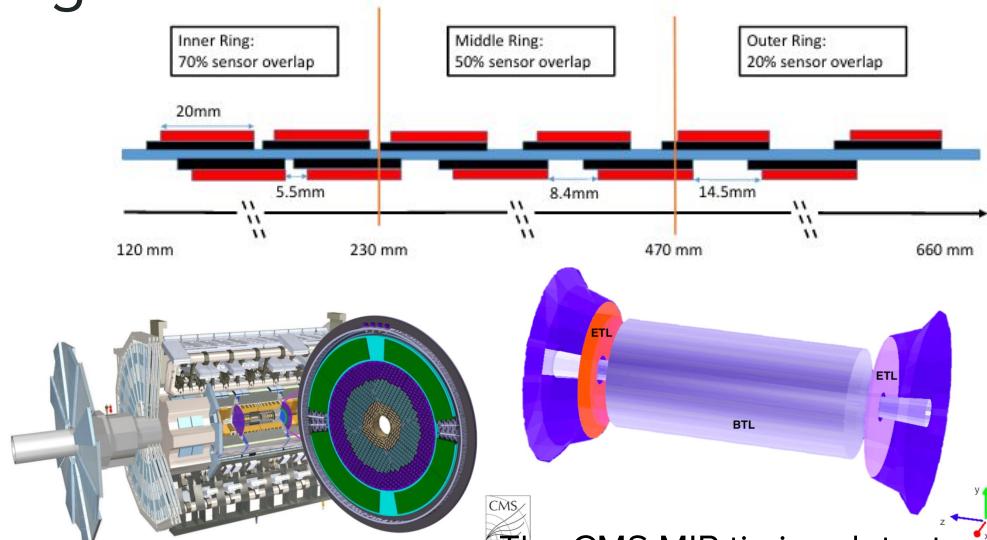
- 3 layers inside beam pipe up to 5-15 mm from beam line with 0.05% X_0 per layer
- 1e6 pixels cm^{-2} in innermost layers: $10 \mu\text{m} \times 10 \mu\text{m}$
- 3 μm resolution
- 7 layers outside beam pipe with 0.5 % X_0 per layer
- Time of flight detector with 20 ps time resolution depleted MAPS/SPADs:
 $\Phi_{\text{eq}} = 1\text{e}12 \text{ cm}^{-2}$
- Innermost layer $\Phi_{\text{eq}} = 3\text{e}14 \text{ cm}^{-2}$
 - 5e15





ATLAS High Granularity Timing Detector

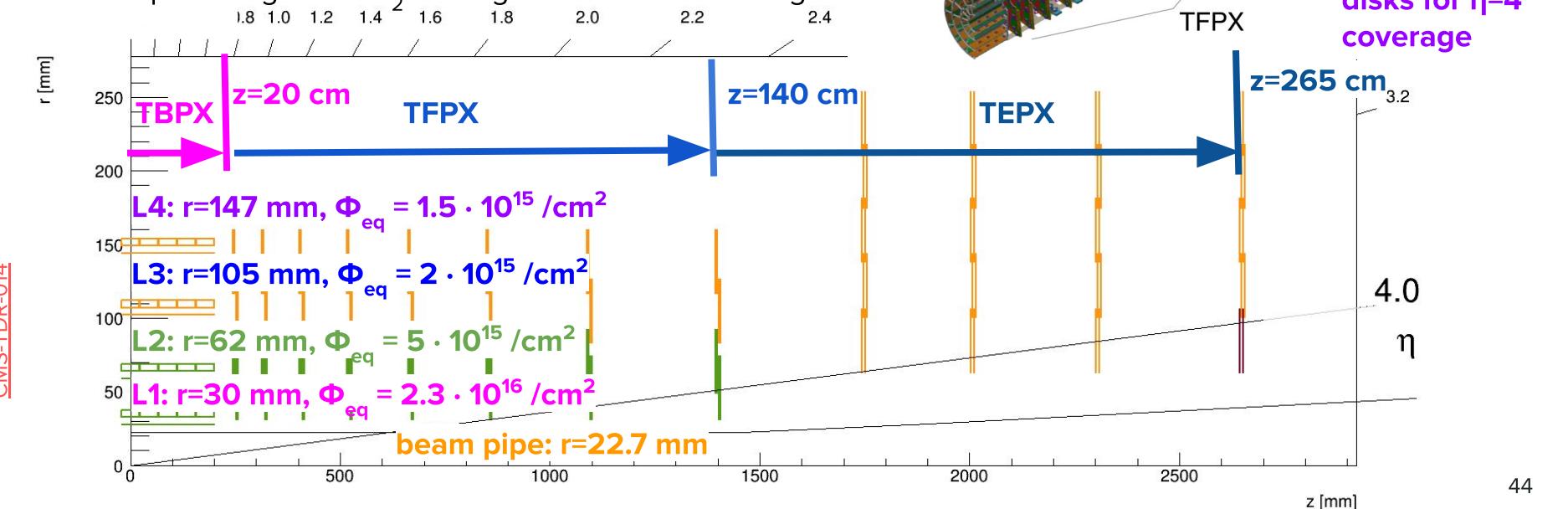
- High lumi LHC: 4000 fb^{-1}
- $z = \pm 3.5 \text{ m}$
- Outside ITk
- In front of endcap calorimeters
- $r = 120\text{-}640 \text{ mm}$
- CO_2 cooling @ -30°C
- Overlapping double modules
- Time resolution per track (per hit)
 $25 \text{ ps} (35 \text{ ps})$ for $r = 120 \text{ mm}$
- After 4000 fb^{-1} : $42 \text{ ps} (60 \text{ ps})$
- $\Phi_{\text{eq}} = (5.5) 8.3\text{e}15 \text{ cm}^{-2}$, $7.5 (3.3) \text{ MGy}$
- **Half will be replaced**: < 230 mm after 1000 fb^{-1} , < 470 after 2000 fb^{-1}



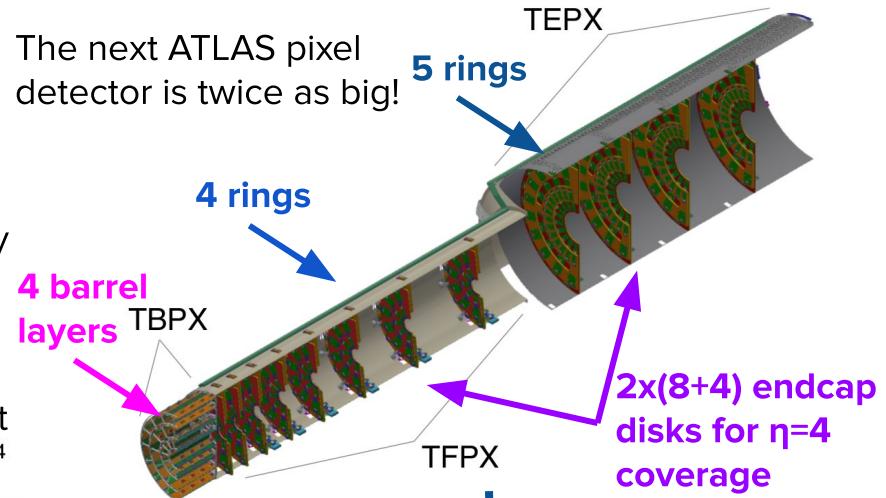
The CMS MIP timing detector also has a barrel layer with silicon photomultipliers

CMS phase 2 pixel detector

- Coverage up to $\eta=4$ (from $\eta=2.5$) and high-rate capability
- Smaller pixels of **25x100** or **50x50** μm^2
- 3D sensors option for innermost layer
- RD53 65nm CMOS ASIC for CMS and ATLAS
- Serial powering and CO_2 cooling for low material budget



The next ATLAS pixel
detector is twice as big!

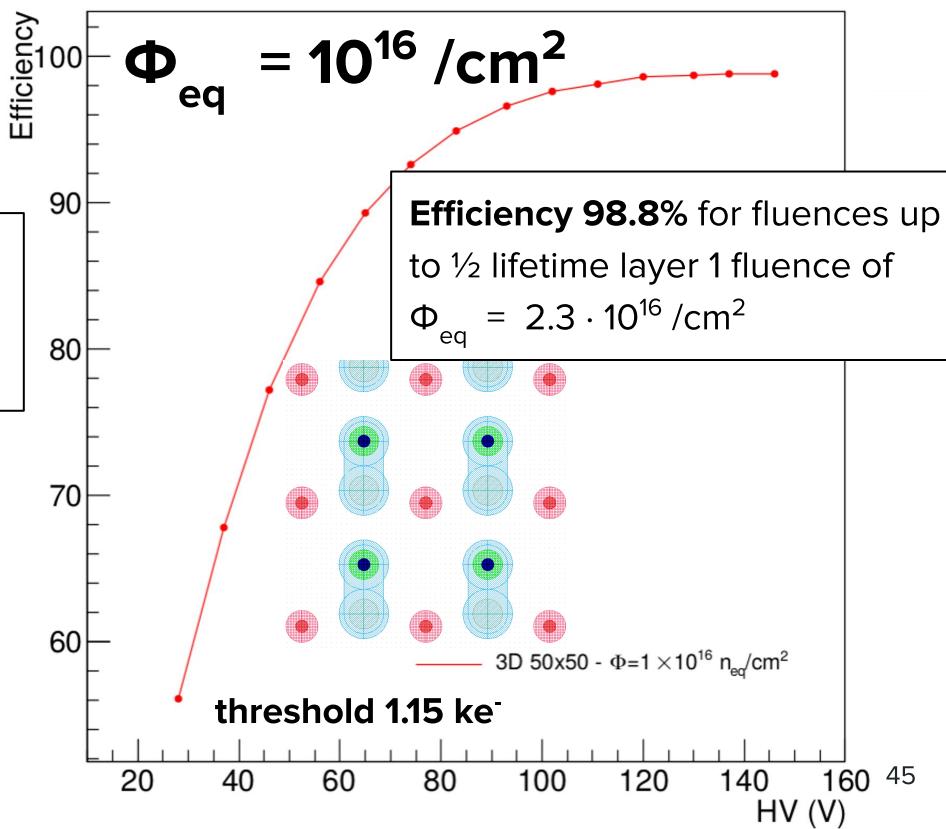
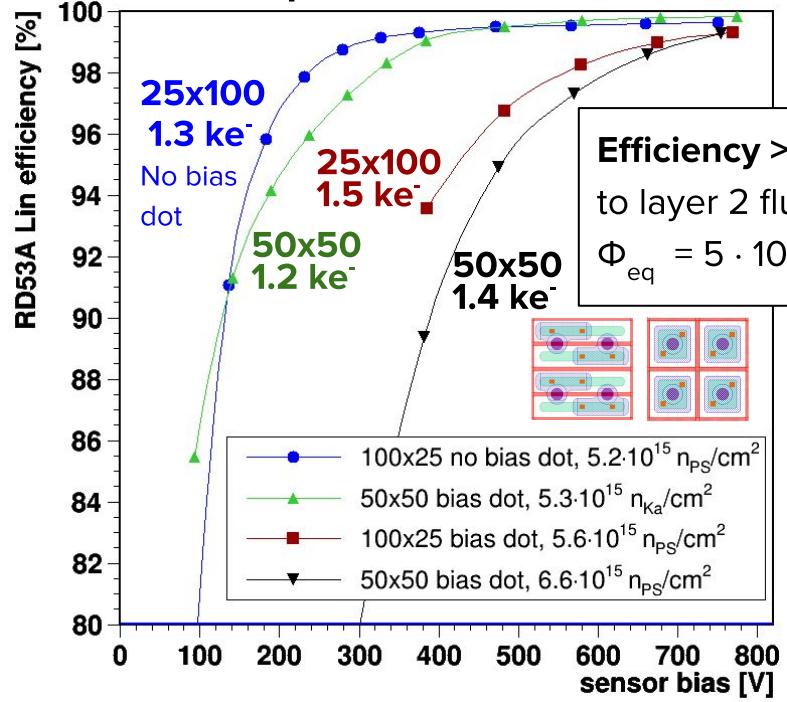


Planar sensors

150 μm n⁺ in p

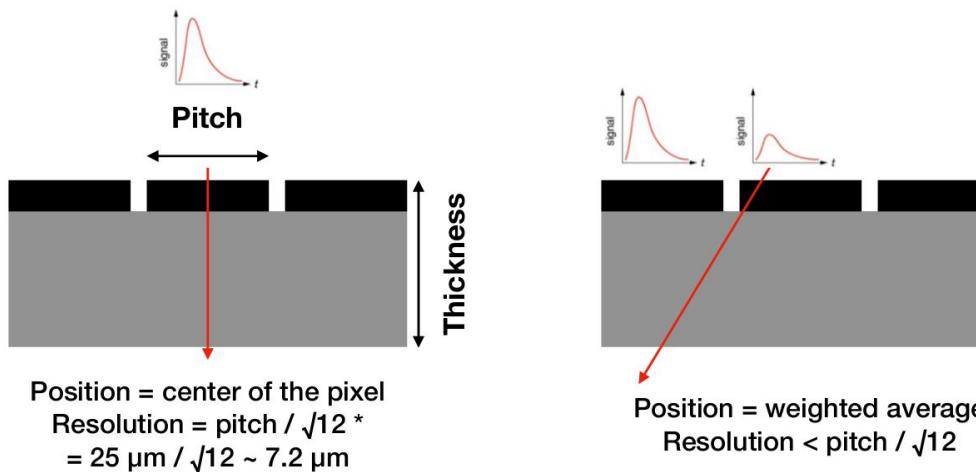
3D sensors

$$\Phi_{\text{eq}} > 5 \cdot 10^{15} / \text{cm}^2$$



Charge sharing improves resolution

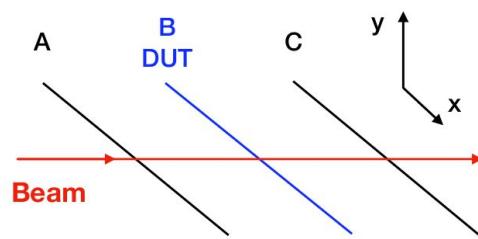
For physics results the resolution obtained with new pixel module is important:



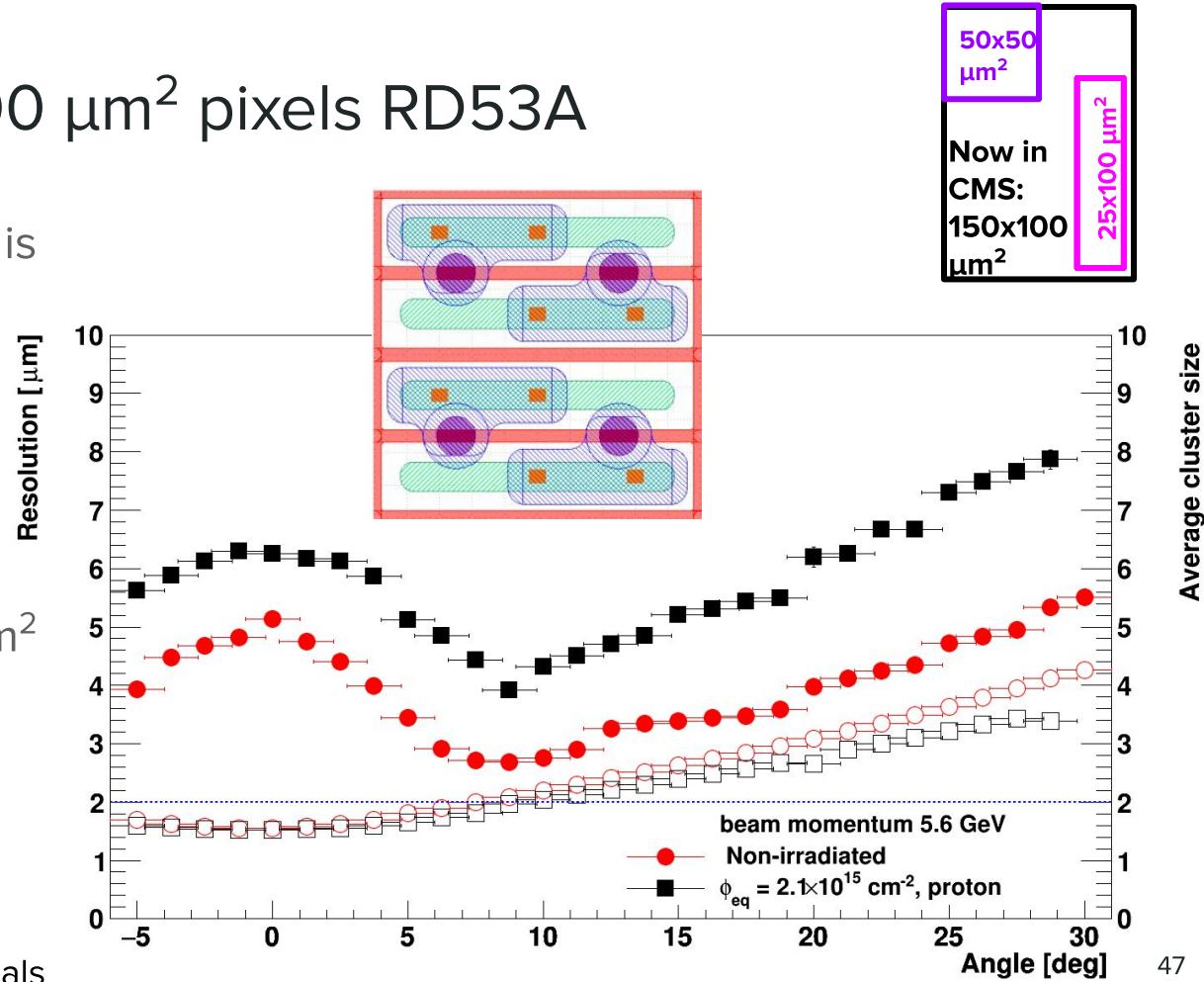
Resolution improves with angle: charge sharing gives a weighted average
→ better resolution

Resolution for 25x100 μm^2 pixels RD53A

- Optimal charge sharing is for 9.5°
- Best hit resolution 2.68 μm before irradiation
- Best hit resolution 3.92 μm for proton-irradiated sensor at $\Phi_{\text{eq}} = 2 \cdot 10^{15}/\text{cm}^2$



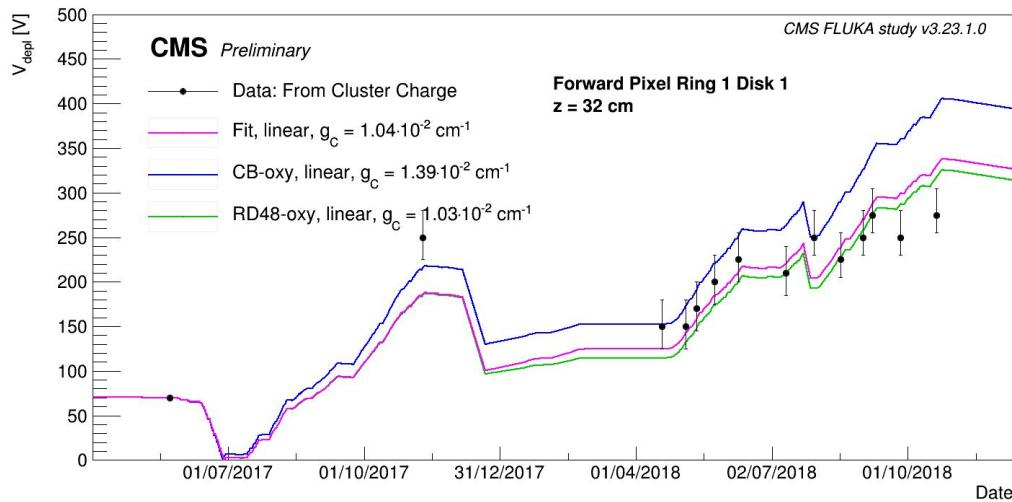
Resolution obtained with triplet residuals



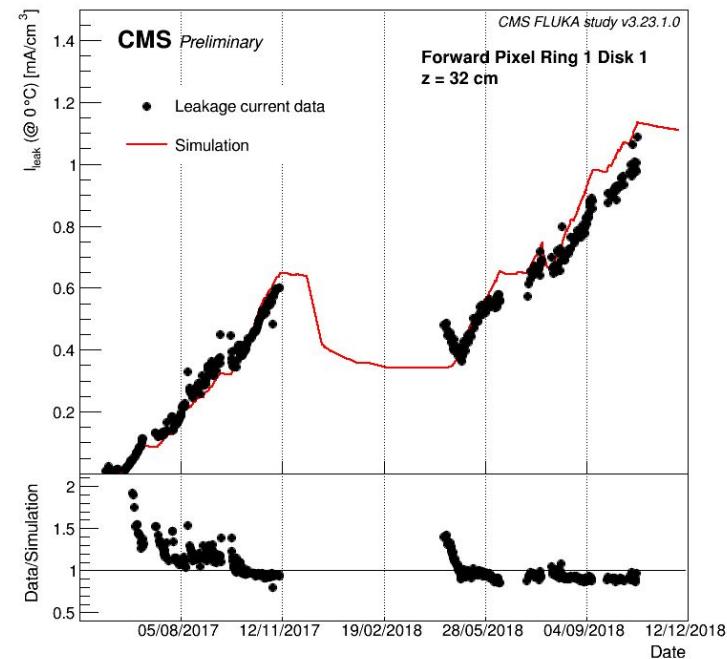
Radiation effects in the CMS forward pixel detector

- On-module temperatures better understood than in barrel detector

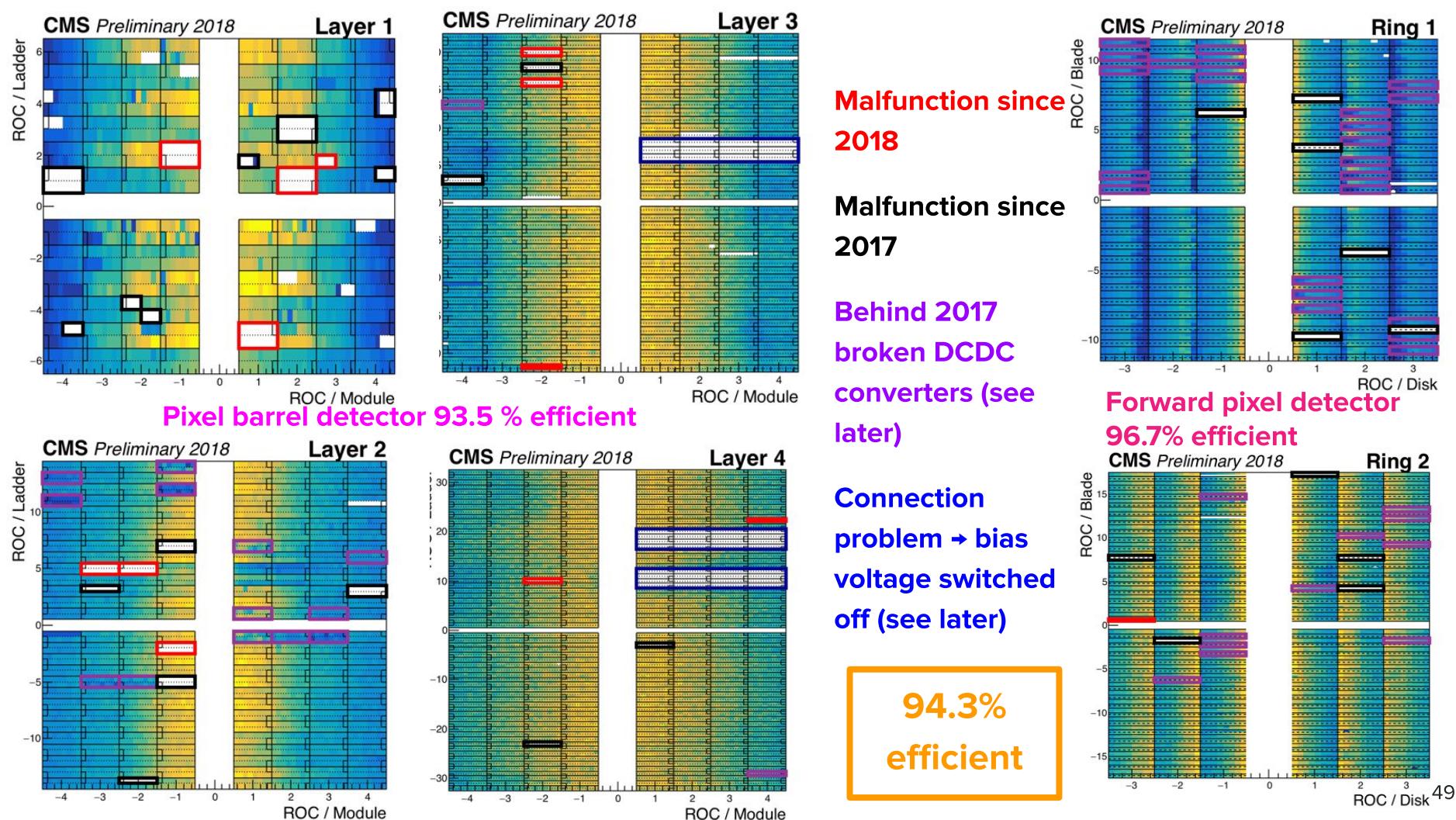
Phase-1 Forward Pixel - Full depletion voltage vs day



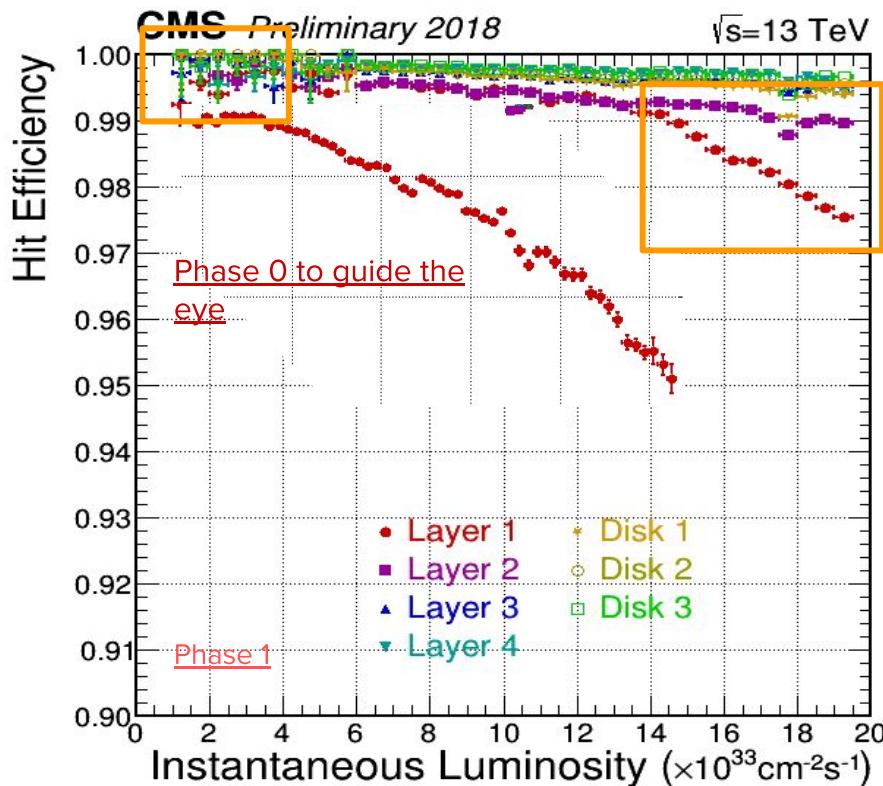
Phase-1 Forward Pixel - Leakage current vs day



Leakage current depends on fluence and temperature



Detector performance



Data and time stamp are buffered until a trigger or reset arrives.

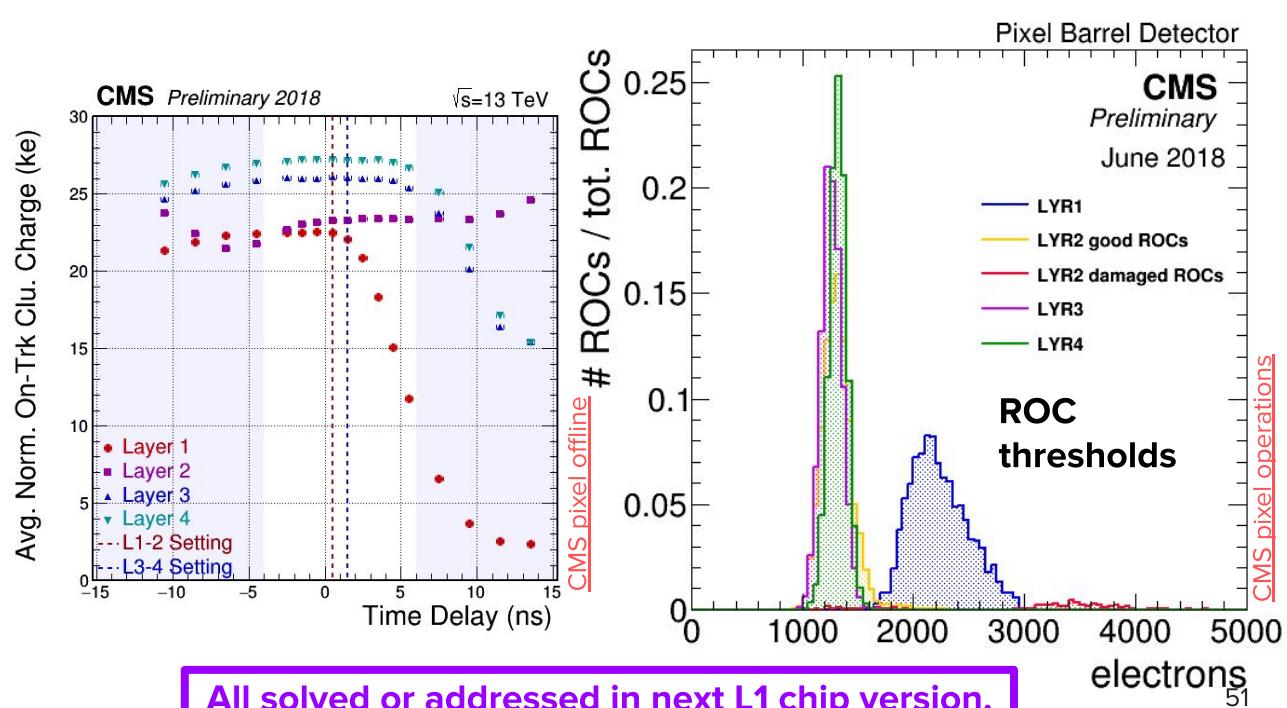
Overall a high efficiency: good performance!

Inefficiency from synchronization loss between data and time stamp buffer at high and low rates:

- low $L \sim 1E33/cm^2/s^2$
- high $L > 1.4E34/cm^2/s^2$
- solved by 70 Hz CMS reset rate

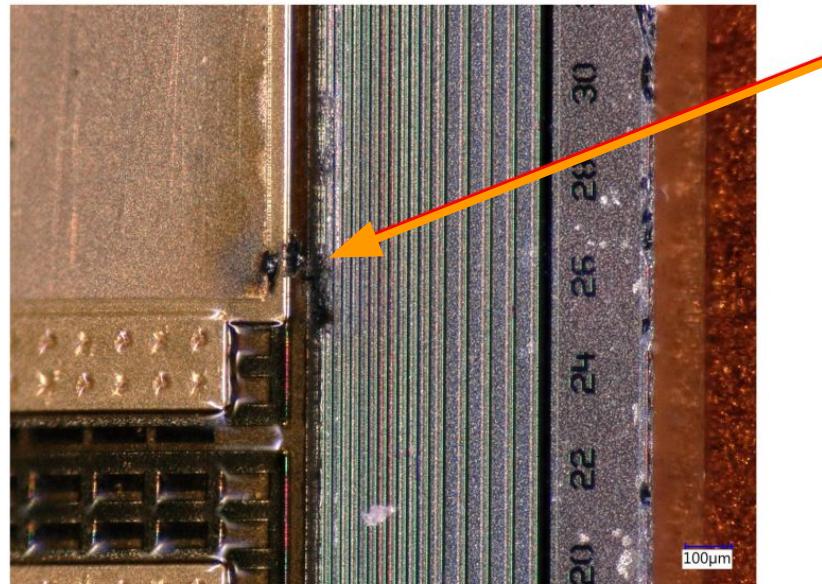
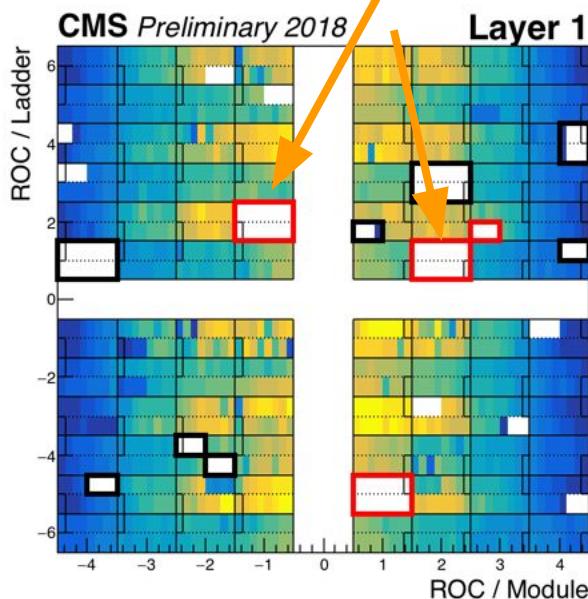
Layer 1 chip PROC600: timing, crosstalk, inefficiency

- Layer 1 readout **chip**
speed ½ clock
faster than layer 2
ROC → **not enough delay setting**
granularity: L1, L2 on same clock
- **High thresholds** resulting from crosstalk → “noise” hits solved with software



More problems with layer 1

- HV problem on the High Density Interconnect (HDI), the flex on the module: shorts in June 2018
- Stayed at 450 V in 2018



From Danek
Kotlinski

Stuck TBMs and malfunctioning DCDC converters

power supply unit (PSU)

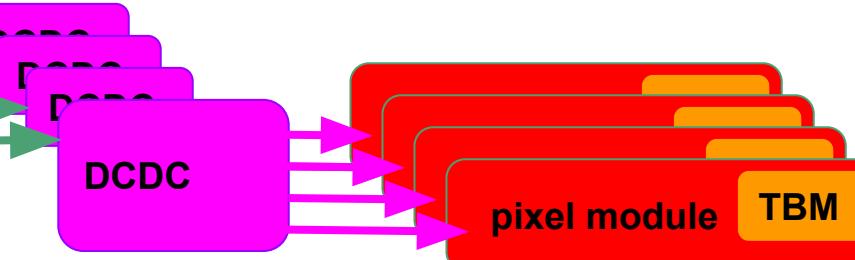
3-4 DCDCs powered by one PSU

2: irradiated DCDCs stopped functioning in disabled state

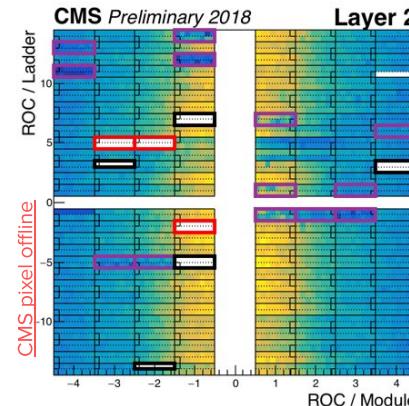
- Increased leakage current as a result of one transistor
- 63/1216 at end of 2017 stopped functioning, another 333 had high current

2018: powercycling with PSU. No DCDC broke.

2020+: new DCDCs, new L1 TBMs.



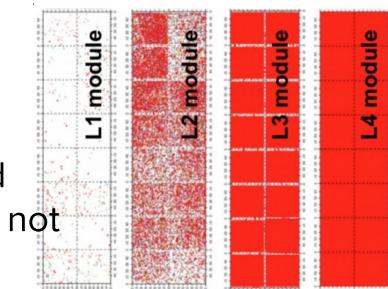
1-4 modules powered by 1 DCDC



Layer 2 damaged chips

1: token bit manager (TBM)

- 30 single event upsets (SEUs)/ fb^{-1} in L1 transistor in TBM latch sets TBM to 'no readout' mode: "**stuck TBMs**"
- recovery only with **power cycle**. Lowest granularity: one DCDC converter.

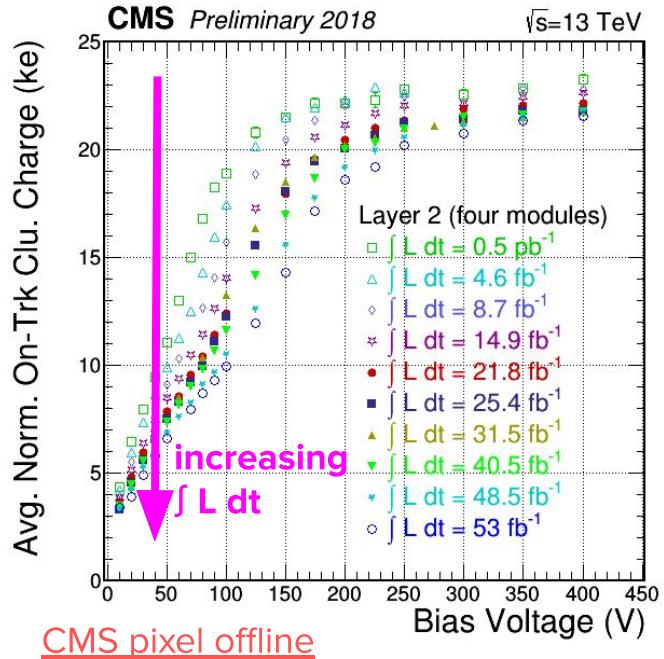


3: readout chips

- module power and bias voltage grouping not the same

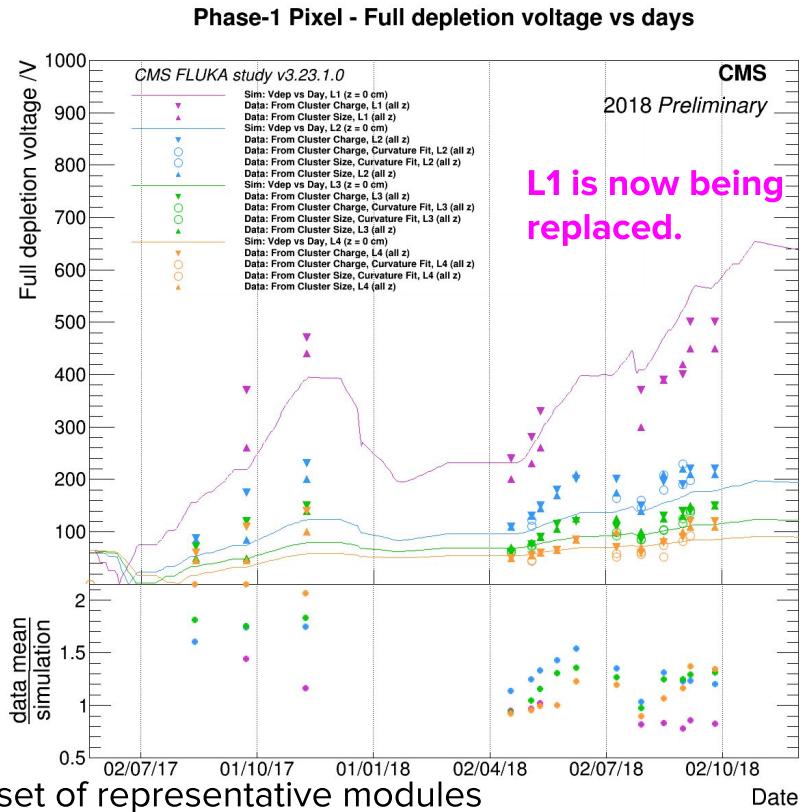
HV on, LV off caused chip damage from sensor leakage current: 8/96 L1 modules lost in 2017

Radiation effects on depletion voltage in CMS



Regular sensor bias voltage scans on subset of representative modules

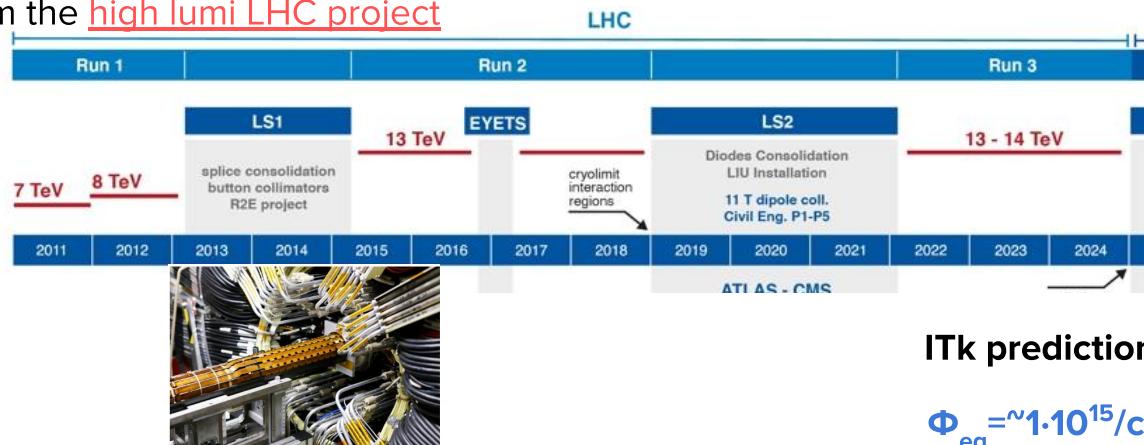
Simulation with effective space charge Hamburg model ($E_{\text{eff}} = 1.21 \text{ eV}$), fluence from DPMJet + FLUKA 3.23.1.0



Operational voltages at end of run 2:
L1: 450V
L2: 300V
L3-L4: 250V
Ring 1: 350V
Ring 2: 300V

Fluences in the ATLAS pixel detector

From the [high lumi LHC project](#)



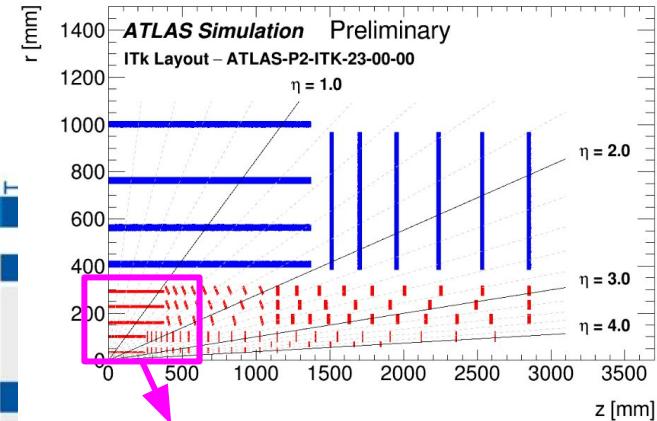
Current ATLAS pixel detector

$$\text{Layer-2: } r=122.5 \text{ mm} \quad \Phi_{\text{eq}} = \sim 6 \cdot 10^{13} / \text{cm}^2$$

$$\text{Layer-1: } r=88.5 \text{ mm} \quad \Phi_{\text{eq}} = \sim 1.4 \cdot 10^{14} / \text{cm}^2$$

$$\text{B-Layer: } r=50.5 \text{ mm} \quad \Phi_{\text{eq}} = \sim 3 \cdot 10^{14} / \text{cm}^2$$

$$\text{IBL: } r=33.5 \text{ mm} \quad \Phi_{\text{eq}} = \sim 6 \cdot 10^{14} / \text{cm}^2$$



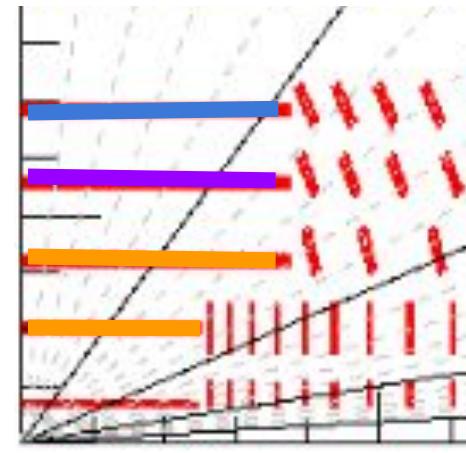
ITk predictions

$$\Phi_{\text{eq}} = \sim 1 \cdot 10^{15} / \text{cm}^2$$

$$\Phi_{\text{eq}} = \sim 4 \cdot 10^{15} / \text{cm}^2$$

$$\Phi_{\text{eq}} = \sim 4 \cdot 10^{15} / \text{cm}^2$$

$$3D: \quad \Phi_{\text{eq}} = \sim 8.1 \cdot 10^{16} / \text{cm}^2$$

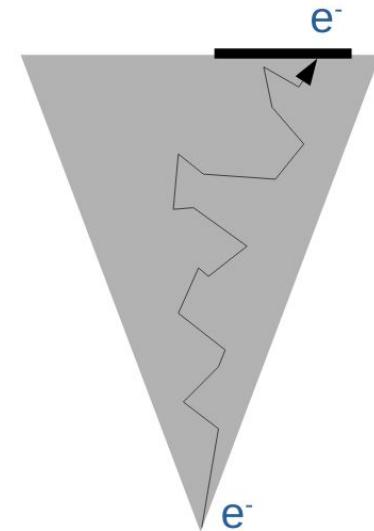


Allpix² charge propagation

Generic Propagation module:

- Mobility from E and B fields with [Jacoboni, Canali et al.](#)
- Make steps with each the drift velocity and diffusion offset
- Steps for groups of charge carriers
- Default number of carriers per group: 10
- Default propagated charge: electrons

[From Paul Schütze](#)



**Generic
propagation**

Implementation of trapping

By Sinuo Zhang

Propagate only **part of the charges in a group** according to

$$Q(t) = Q(t=0) \exp[-t/\tau]$$

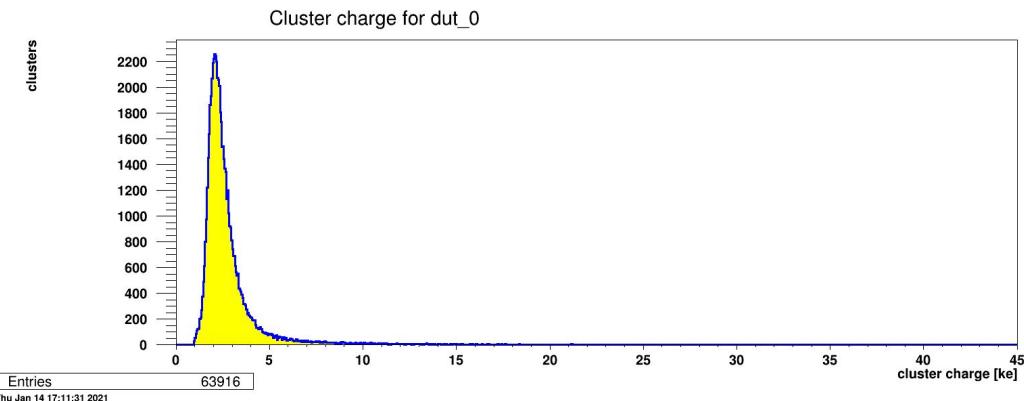
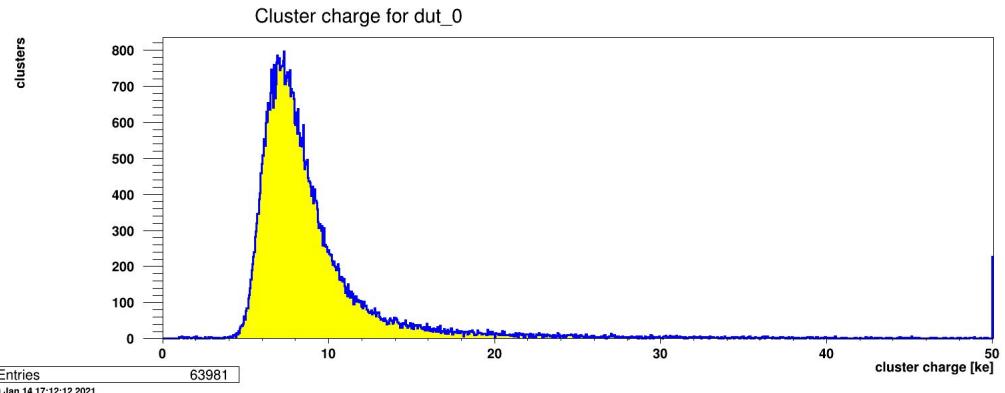
Effective trapping time by Kramberger et al

$$\frac{1}{\tau_{\text{eff}_{e,h}}} = \beta_{e,h} \Phi_{\text{eq}}$$

$$\beta_h = (6.1 \pm 0.3) \times 10^{-16} \text{ cm}^2/\text{ns.} \quad \beta_e = (4.2 \pm 0.3) \times 10^{-16} \text{ cm}^2/\text{ns}$$

Cluster charge after trapping

- Unirradiated
- 100k events
- DUT RD53
- Threshold $1000e^-$
- Trapping $\Phi_{eq} = 5e15 /cm^2$



Further possibilities for trapping and simulation

- Temperature dependent trapping
 $\kappa_e = -0.86 \pm 0.06$ $\kappa_h = -1.52 \pm 0.07$
- Electric field dependent trapping

$$\beta_{e,h}(T) = \beta_{e,h}(T_0) \left(\frac{T}{T_0} \right)^{\kappa_{e,h}}$$

[From Kramberger et al](#)

$$\tau(E) = \tau_0 + \tau_1 \cdot E$$

[Thesis by Thomas Pöhlsen](#)

- Error bars from errors on parameters: errors are not implemented / accounted for in Allpix²
- Use [corryreckan](#) for alignment procedure and analysis (see also this [tutorial](#))

Lab infrastructure for sensor characterization



Laser diodes with 660, 980,
1060 nm



Commissioning a 200 fs
pulse TPA-TCT setup

Laser setups used for

- Characterization of timing properties
- Characterization of sensor material
 - Can be used as input for TCAD studies
- Various other instruments:
 - X-ray tube 90 kV
 - Various radioactive sources
 - Oscilloscopes up to 33 GHz
 - Süss PA300 probe station
 - Keithley SCS4200 semiconductor characterisation station
 - Small scanning electron microscope
 - Wire bonder
- Experience with TCAD Sentaurus

Detector R&D lab infrastructure for sensor characterization



Laser diodes with 660, 980,
1060 nm

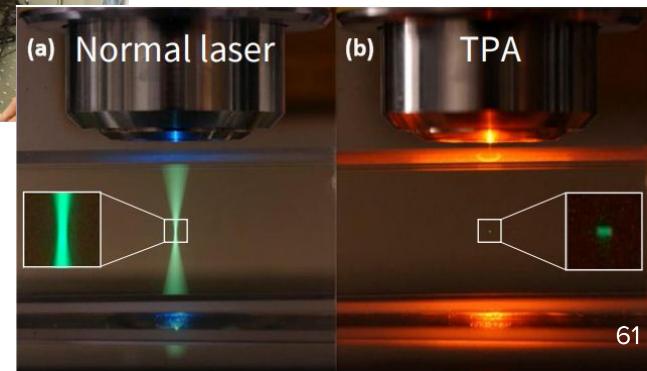


Commissioning a 380
femtosecond pulse
“two-photon-absorption
transient current technique”
TPA-TCT setup

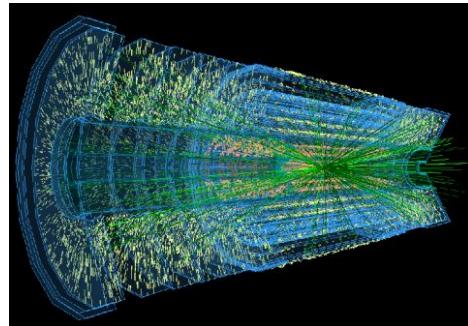
Laser setup already used to
measure time resolution of
Timepix chip.

Will use TPA setup for
precise 3D characterization
of MAPS as well.

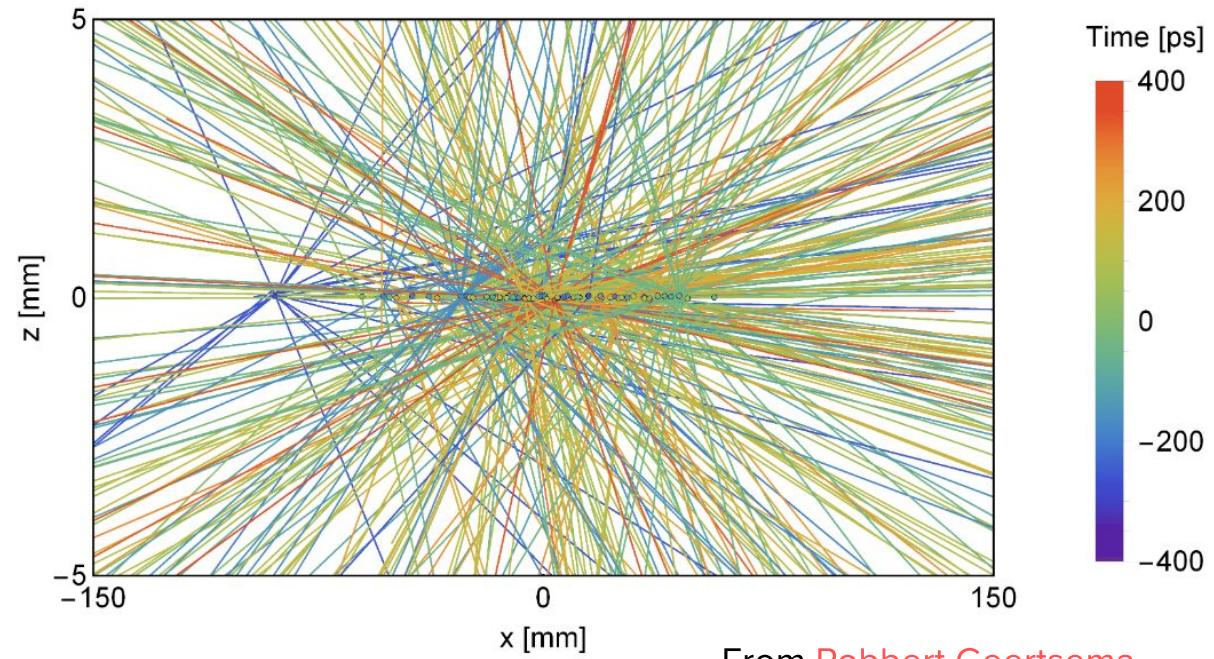
380 fs – 5.5 nJ – 1 µm wide spot
fast – powerful – precise



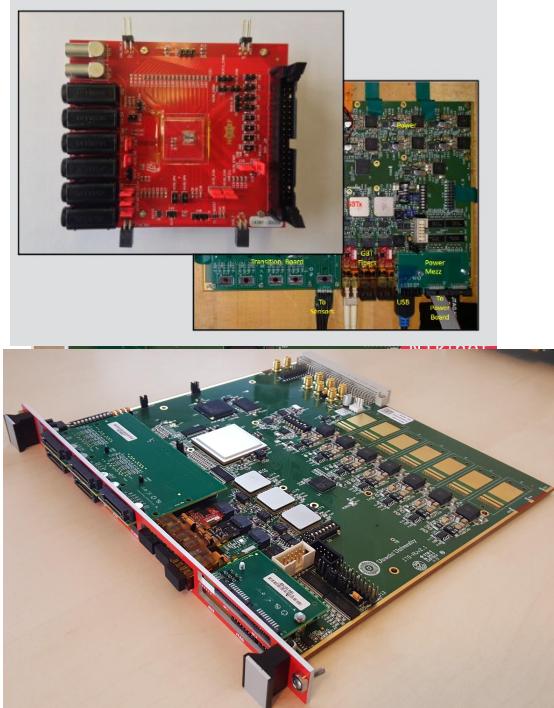
Distinguish vertices based on timing information



Window: 800 ps

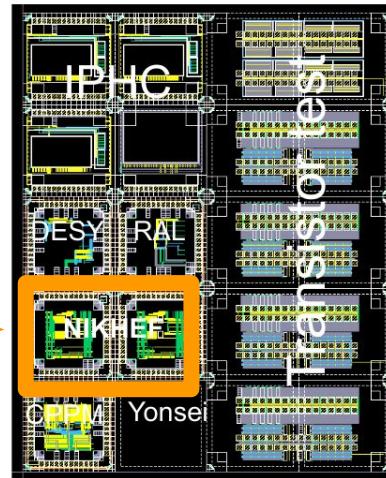


Towards fast timing with MAPS



Nikhef was involved in ASIC design and readout of TowerJazz **180 nm ALPIDE** for the Alice ITS2 system

First MLR submission



We currently defining our fast timing sensor and ASIC development program with Nikhef ET, ALICE and LHCb -- and eventually ATLAS? =)

**Continue development of TJ
65 nm
Investigate timing with MAPS**

Nikhef is involved in design of TowerJazz **65 nm ALPIDE** for the ALICE ITS3 system

CMS and ATLAS pixel detectors in LS2

Now: 118 /fb Run 3 **2023 (2024)**: 220 (320) /fb
 Fluences could triple!



2.8 Mrad / Φ_{eq} = $5 \cdot 10^{13} / \text{cm}^2$

L4: $r=160 \text{ mm}$

5.2 Mrad / Φ_{eq} = $9 \cdot 10^{13} / \text{cm}^2$

L3: $r=109 \text{ mm}$

8.5 Mrad / Φ_{eq} = $1.8 \cdot 10^{14} / \text{cm}^2$

L2: $r=66 \text{ mm}$

40.1 Mrad / Φ_{eq} = $7.9 \cdot 10^{14} / \text{cm}^2$

L1: $r=29 \text{ mm}$

beam pipe: $r=22.5 \text{ mm}$

50.0 cm

Fluences as of today, from FLUKA 3.23.1.0



[From Kerstin Lantsch](#)



Layer-2: $r=122.5 \text{ mm}$

$\Phi_{eq} = \sim 6 \cdot 10^{13} / \text{cm}^2$

Layer-1: $r=88.5 \text{ mm}$

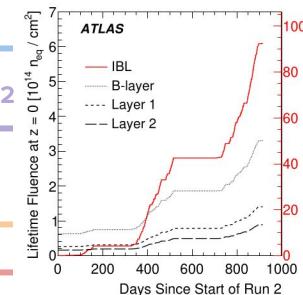
$\Phi_{eq} = \sim 1.4 \cdot 10^{14} / \text{cm}^2$

B-Layer: $r=50.5 \text{ mm}$

$\Phi_{eq} = \sim 3 \cdot 10^{14} / \text{cm}^2$

IBL: $r=33.5 \text{ mm}$

$\Phi_{eq} = \sim 6 \cdot 10^{14} / \text{cm}^2$



[From ATLAS-IDET-2017-10](#)

